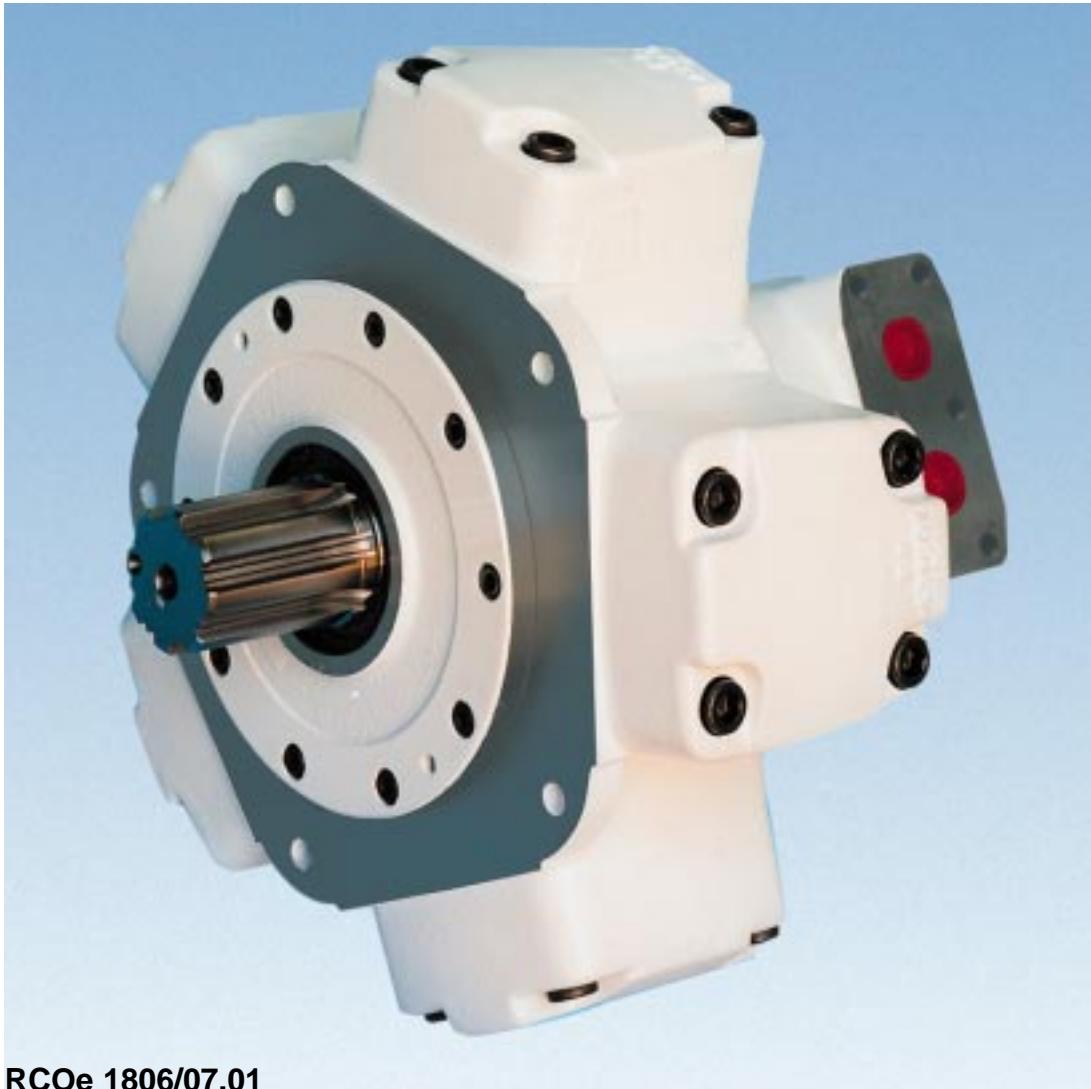


**DENISON CALZONI**  
**Radial Piston Motor**  
**Type MR, MRE**

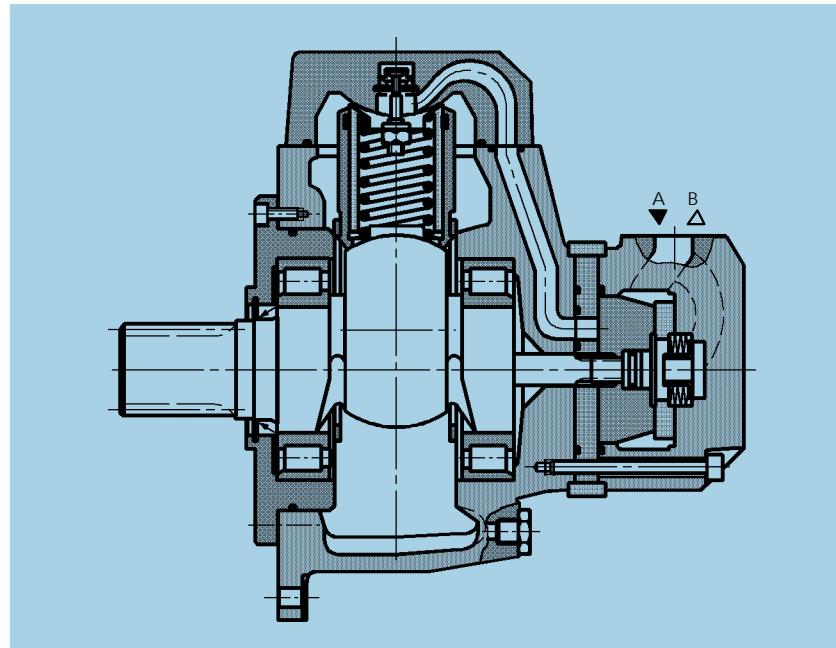


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**DENISON** **CALZONI**

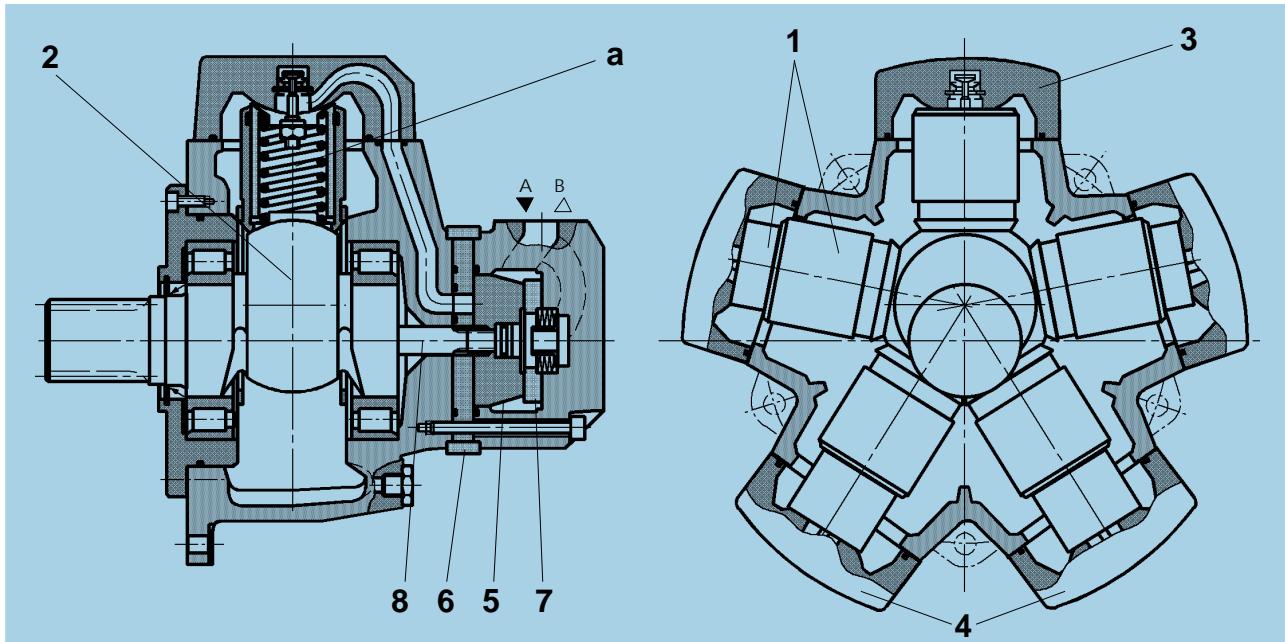
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## GENERAL CHARACTERISTICS



<b>CONSTRUCTION</b>	Fixed displacement radial piston motor
<b>TYPE</b>	MR ; MRE
<b>MOUNTING</b>	Front flange mounting
<b>CONNECTION</b>	Connection flange
<b>MOUNTING POSITION</b>	Any (please note the installation notes on page 34)
<b>BEARING LIFE, RADIAL LOAD</b>	See page 22 and 23
<b>DIRECTION OF ROTATION</b>	Clockwise, anti-clockwise - reversible
<b>FLUID</b>	HLP mineral oils to DIN 51 524 part 2; Fluid type HFB, HFC and Bio-fluids on enquiry. FPM seals are required with phosphorous acid-Ester (HFD)
<b>FLUID TEMPERATURE RANGE</b>	$t$ °C – 30° to + 80°
<b>VISCOSITY RANGE <sup>1)</sup></b>	$\eta$ mm <sup>2</sup> /s 18 to 1000: Recommended operating range 30 to 50 (see fluid selection on page 6)
<b>FLUID CLEANLINESS</b>	Maximum permissible degree of contamination of fluid NAS 1638 Class 9. We therefore recommend a filter with a minimum retention rate of $\beta_{10} \geq 75$ . To ensure a long life we recommend class 8 to NAS 1638. This can be achieved with a filter, with a minimum retention rate of $\beta_5 \geq 100$ .

1) For different values of viscosity please contact DENISON Calzoni



## FUNCTIONAL DESCRIPTION

The outstanding performance of this motor is the result of an original and patented design. The principle is to transmit the effort from the stator to the rotating shaft (2) by means of a pressurized column of oil (a) instead of the more common connecting rods, pistons, pads and pins.

This oil column is contained by a telescopic cylinder (1) with a mechanical connection at the lips at each end which seal against the spherical surfaces of the cylinder-heads (3) and the spherical surface of the rotating shaft (4).

These lips retain their circular cross section when stressed by the pressure so there is no alteration in the sealing geometry. The particular selection of materials and optimisation of design has minimized both the friction and the leakage.

Another advantage of this design stems from the elimination of any connecting rods, the cylinder can only expand and retract linearly so there are no transverse components of the thrust. This means no oval wear on the moving parts and no side forces on the cylinder joints.

A consequence of this novel design is a significant reduction in weight and overall size compared with other motors of the same capacity.

## TIMING SYSTEM

The timing system is realized by means of a rotary valve (5) driven by the rotary valve driving shaft (8) that it is connected to the rotating shaft.

The rotary valve rotates between the rotary valve plate (6) and the reaction ring (7) which are fixed with the motor's housing. This timing system is also of a patented design being pressure balanced and self compensating for thermal expansion.

## EFFICIENCY

The advantages of this type of valve coupled with a revolutionary cylinder arrangement produce a motor with extremely high values of mechanical and volumetric efficiency. The torque output is smooth even at very low speed and the motor gives a high performance starting under load.

# TECHNICAL DATA - MOTOR TYPE MR - MRE

Size Motor version		Displace- ment	Moment inertia of rotating parts	Theore- tical specific torque	Min. start. torque / Theore- tical torque	Maximum Pressure				Speed range		Maximum output power		Weight	
						input				flushing		flushing			
						cont.	int.	peak	A+B	Drain	without	with	without	with	
		V	J		%	p	p	p	p	p	n	n	P	P	m
		cm <sup>3</sup>	kg cm <sup>2</sup>	Nm/bar		bar	bar	bar	bar	bar	rpm	rpm	kW	kW	kg
M R	<b>33</b>	32,1	4,32	0,50	90	5 (15 bar with "F1" shaft seal)	250	300	420	400	1-1400	1-1400	6,6	10	30
	<b>57</b>	56,4	4,76	0,90	90						1-1300	1-1300	11	17	30
	<b>73</b>	72,6	14,03	1,20	90						1-1200	1-1200	15	20	38
	<b>93</b>	92,6	15,11	1,50	90						1-1150	1-1150	17	25	38
	<b>110</b>	109,0	16,19	1,70	90						1-1100	1-1100	18	28	38
	<b>125</b>	124,7	56,88	2,00	90						1-900	1-900	17	25	46
	<b>160</b>	159,7	57,50	2,54	90						1-900	1-900	20	30	46
	<b>190</b>	191,6	58,20	3,05	90						1-850	1-850	24	36	46
	<b>200</b>	199,2	57,15	3,20	90						1-800	1-800	25	38	50
	<b>250</b>	250,9	60,80	4,00	90						1-800	1-800	32	48	50
	<b>300</b>	304,1	65,43	4,80	90						1-750	1-750	35	53	50
	<b>350</b>	349,5	225,90	5,57	90						1-640	1-640	41	62	77
	<b>450</b>	451,6	229,80	7,20	90						1-600	1-600	46	75	77
	<b>600</b>	607,9	265,07	9,70	90						1-520	1-520	56	84	97
	<b>700</b>	706,9	358,40	11,30	90						1-500	1-500	65	97	97
	<b>1100</b>	1125,8	451,50	17,90	90						0,5-330	0,5-330	77	119	140
	<b>1600</b>	1598,4	666,43	25,40	90						0,5-260	0,5-260	96	144	209
	<b>1800</b>	1809,6	854,10	28,80	90						0,5-250	0,5-250	103	153	209
	<b>2400</b>	2393,0	2835,40	38,10	90						0,5-220	0,5-220	120	183	325
	<b>2800</b>	2792,0	2975,70	44,50	90						0,5-215	0,5-215	127	194	325
	<b>3600</b>	3636,8	4851,40	57,90	90						0,5-150	0,5-180	123	185	508
	<b>4500</b>	4502,7	5015,10	57,90	91						0,5-130	0,5-170	140	210	508
	<b>6500</b>	6460,5	11376,6	103,57	91						0,5-110	0,5-130	165	240	800
	<b>7000</b>	6967,2	11376,6	111,39	91						0,5-100	0,5-130	170	250	800
M R E	<b>330</b>	332,4	65,50	5,30	90	5 (15 bar with "F1" shaft seal)	210	250	350	400	1-750	1-750	32	49	50
	<b>500</b>	497,9	229,80	7,93	90						1-600	1-600	46	70	77
	<b>800</b>	804,2	358,40	12,81	90						1-450	1-450	65	93	97
	<b>1400</b>	1369,5	451,50	21,80	92						0,5-280	0,5-280	77	102	145
	<b>2100</b>	2091,2	854,10	33,30	91						0,5-250	0,5-250	100	148	221
	<b>3100</b>	3103,7	2975,70	49,40	91						0,5-215	0,5-215	125	190	329
	<b>5400</b>	5401,2	5015,10	86,01	92						0,5-120	0,5-160	140	210	512
	<b>8200</b>	8226,4	11376,6	130,90	92						0,5-90	0,5-120	170	250	810

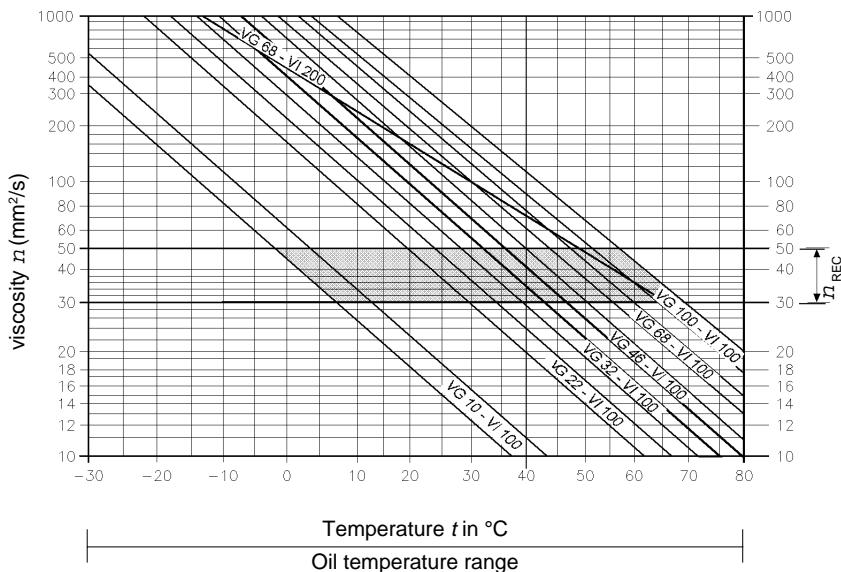
LARGER DISPLACEMENTS ARE AVAILABLE IN THE MRT - MRTE - MRTF MOTOR SERIES

**EXAMPLE:** At a certain ambient temperature, the operating temperature in the circuit is 50°C. In the optimum operating viscosity range ( $\nu_{rec}$ ; shaded section), this corresponds to viscosity grades VG 46 or VG 68; VG 68 should be selected.

**IMPORTANT:** The drain oil temperature is influenced by pressure and speed and is usually higher than the circuit temperature or the tank temperature. At no point in the system, however, may the temperature be higher than 80°C.

If the optimum conditions cannot be met due to the extreme operating parameters or high ambient temperature, we always recommend flushing the motor case in order to operate within the viscosity limits.

Should it be absolutely necessary to use a viscosity beyond the recommended range, you should first contact DENISON Calzoni for confirmation.



## GENERAL NOTES

## OPERATING VISCOSITY RANGE

More detailed information regarding the choice of the fluid can be requested to DENISON Calzoni. Further notes on installation and commissioning can be found on page 34 of this data sheet. When operating with HF pressure fluids or bio-degradable pressure fluids possible limitations of the technical data must be taken into consideration, please see information sheet TCS 85, or consult DENISON Calzoni.

The viscosity, quality and cleanliness of operating fluids are decisive factors in determining the reliability, performance and life-time of an hydraulic component. The maximum life-time and performance are achieved within the recommended viscosity range. For applications that go beyond this range, we recommend to contact DENISON Calzoni.

$$\nu_{rec} = \text{recommended operating viscosity } 30\ldots50 \text{ mm}^2/\text{s}$$

This viscosity refers to the temperature of the fluid entering the motor, and at the same time to the temperature inside the motor housing (case temperature). We recommend to select the viscosity of the fluid based on the maximum operating temperature, to remain within the recommended viscosity range. To reach the value of maximum continuous power the operating viscosity should be within the recommended viscosity range of 30 - 50 cSt.

For limit conditions the following is valid:

$$\nu_{min.abs.} = 10 \text{ mm}^2/\text{s} \text{ in emergency, short term}$$

$$\nu_{min.} = 18 \text{ mm}^2/\text{s} \text{ for continuous operation at reduced performances}$$

$$\nu_{max.} = 1000 \text{ mm}^2/\text{s} \text{ short term upon cold start}$$

The operating temperature of the motor is defined as the greater temperature between that of the incoming fluid and that of the fluid inside the motor housing (case temperature). We recommend that you choose the viscosity of the fluid based on the maximum operating temperature, to remain within the recommended viscosity range (see diagram). We recommend that the higher viscosity grade must be selected in each case. The motor life also depends on the fluid filtration. At least it must correspond to one of the following cleanliness.

class 9 according to NAS 1638

class 6 according to SAE, ASTM, AIA

class 18/15 according to ISO/DIS 4406

In order to assure a longer life a cleanliness class 8 to NAS 1638 is recommended, achieved with a filter of  $b_2=100$ . In case the above mentioned classes can not be achieved, please consult us.

The lower the speed and the case drain pressure, the longer the life of the shaft seal. The maximum permissible housing pressure is

$$p_{max} = 5 \text{ bar}$$

If the case drain pressure is higher than 5 bar it is possible to use a special 15 bar shaft seal (see page 35, Seals, Code "F1").

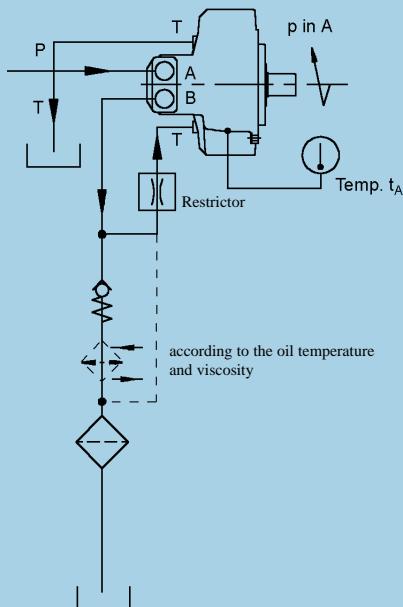
In case of operating conditions with high oil temperature or high ambient temperature, we recommend to use "FPM" seals (see page 35, Seals, Code "V1"). These "FPM" seals should be used with HFD fluids.

## CHOOSING THE TYPE OF FLUID ACCORDING TO THE OPERATING TEMPERATURE

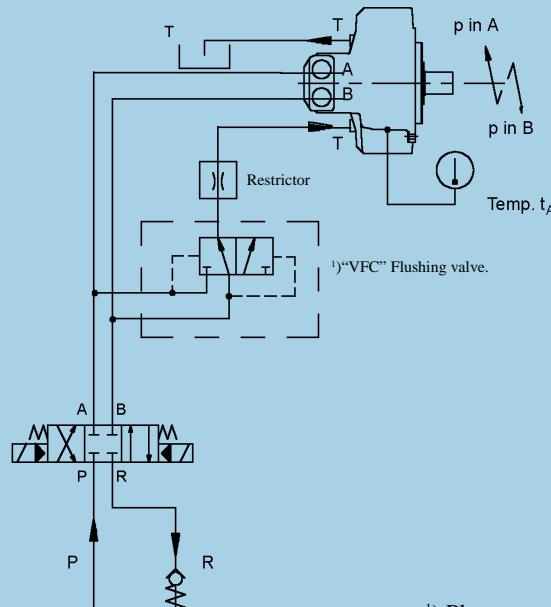
## FILTRATION

## CASE DRAIN PRESSURE

## "FPM" SEALS



FLUSHING CIRCUIT  
(MONO-DIRECTIONAL ROTATION)



FLUSHING CIRCUIT  
(BI-DIRECTIONAL ROTATION)

<sup>1)</sup> Please consult us.

## FLUSHING

The motor case must be flushed when the continuous operating performances of the motor are inside the "Continuous operating area with flushing" (see Operating Diagram from page 8 to page 18), in order to assure the minimum oil viscosity inside the motor case of 30 mm<sup>2</sup>/s (see page 6 - Fluid Selection). The flushing can be necessary also when the operating performances are outside the "Continuous operating area with flushing", but the system is not able to assure the minimum viscosity conditions requested by the motor as specified at page 6.

### NOTE1:

The oil temperature inside the motor case is obtainable by adding 3°C to the motor surface temperature ( $t_A$ , see figures).

### NOTE2:

With the standard shaft seal the maximum drain case pressure is 5 bar. For the selection of the restrictor, please consult us.

## FLOW

TYPE	MOTOR VERSION	FLUSHING FLOW
MR	33, 57, 73, 93, 110	$Q = 5 \text{ l/min}$
MR - MRE	125, 160, 190, 200, 250, 300, 330	$Q = 6 \text{ l/min}$
MR - MRE	350, 450, 500	$Q = 8 \text{ l/min}$
MR - MRE	600, 700, 800, 1100, 1400	$Q = 10 \text{ l/min}$
MR - MRE	1600, 1800, 2100	$Q = 15 \text{ l/min}$
MR - MRE	2400, 2800, 3100, 3600, 4500, 5400, 6500, 7000, 8200	$Q = 20 \text{ l/min}$

# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

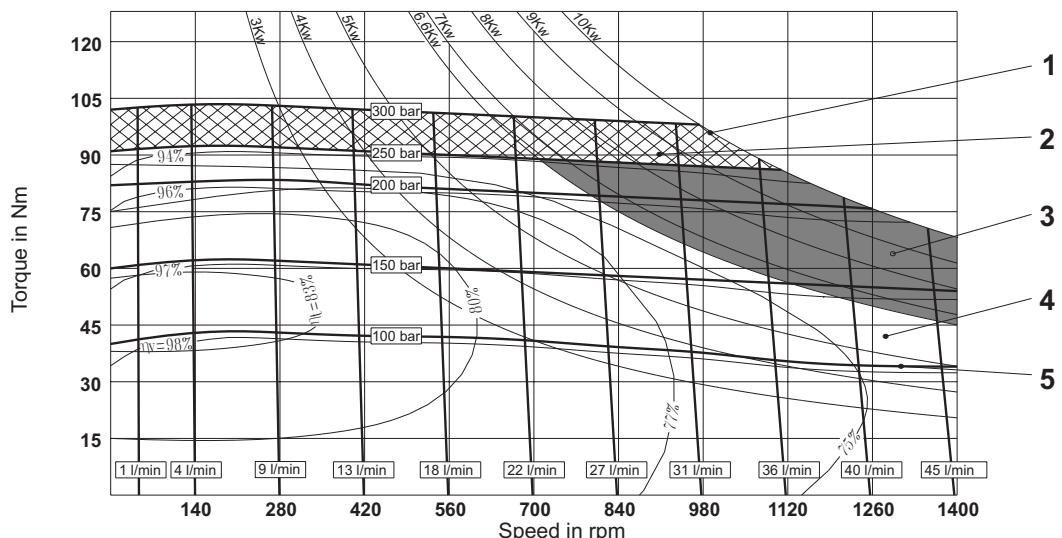
## OPERATING DIAGRAM

(average values) measured at  $\dot{V} = 36 \text{ mm}^3/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

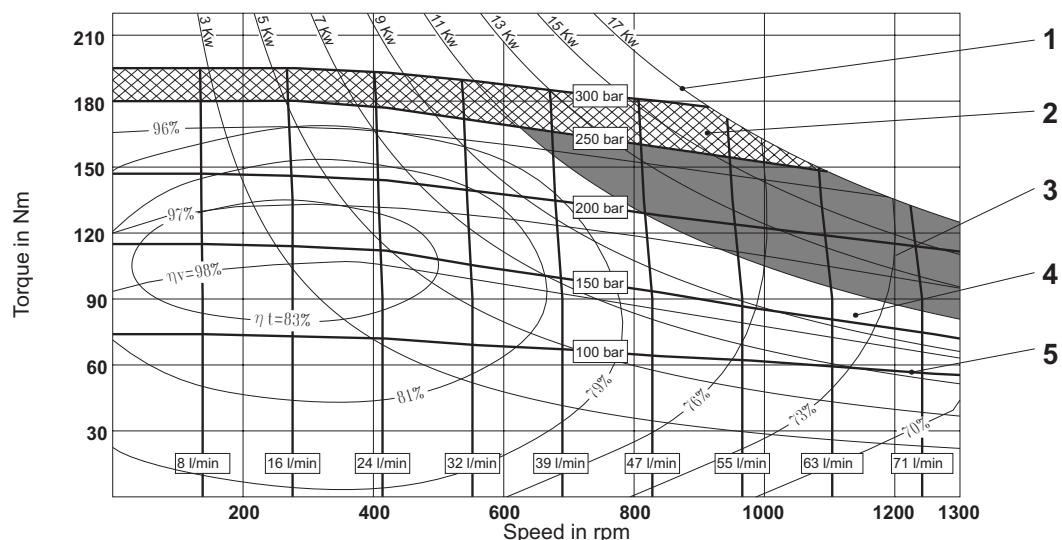
- 1 Output power
- 2 Intermittent operating area
- 4 Continuous operating area

- 3 Continuous operating area with flushing
- 5 Inlet pressure
- $ht$  Total efficiency
- $hv$  Volumeter efficiency

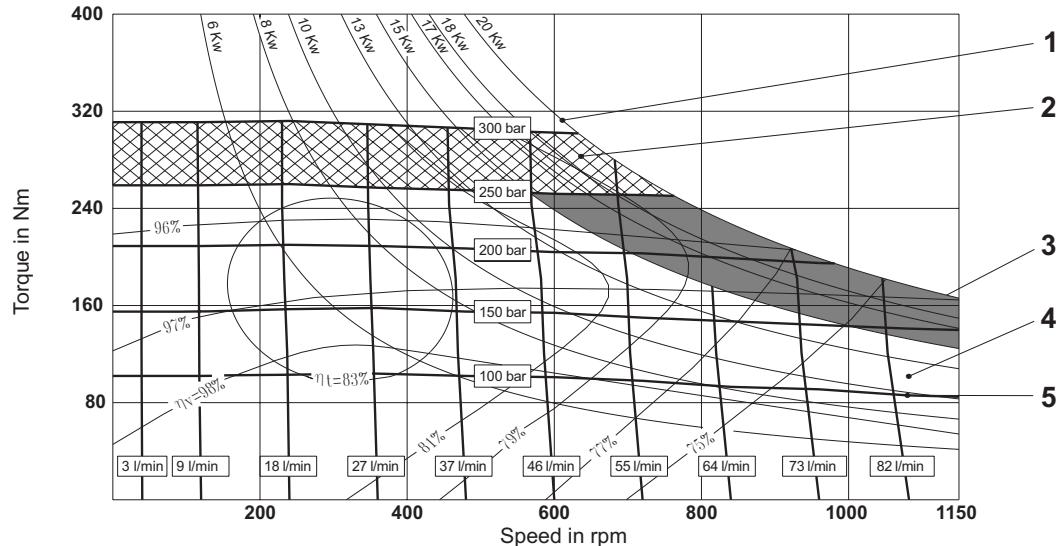
**MR 33**



**MR 57**



**MR 73**



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

## OPERATING DIAGRAM

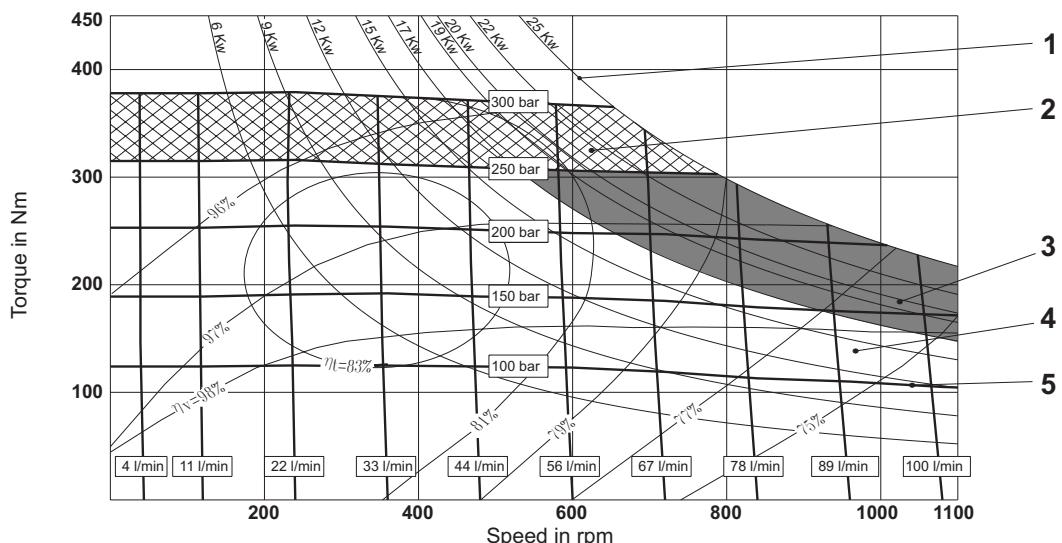
(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

- 1 Output power
- 2 Intermittent operating area
- 4 Continuous operating area

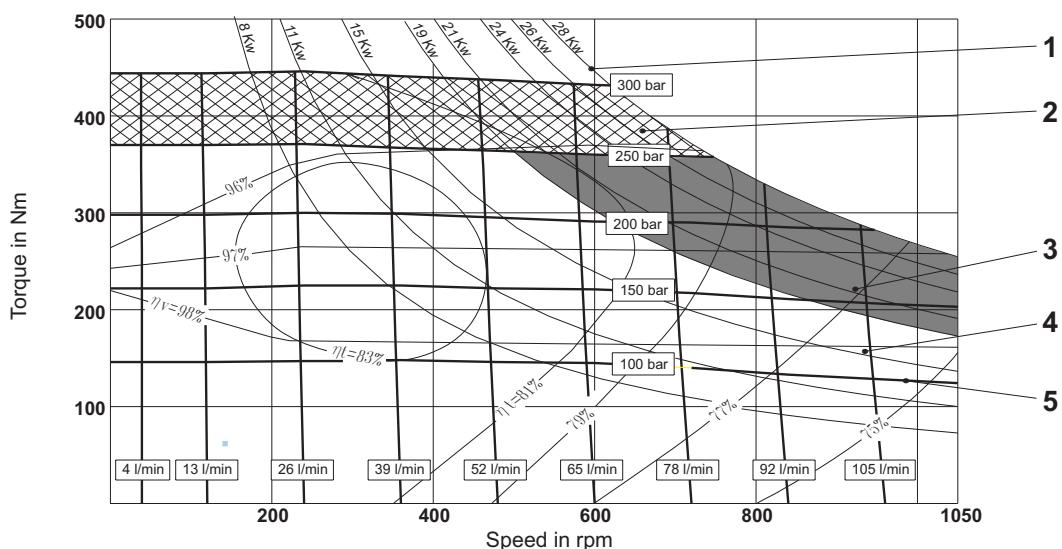
- 2 Intermittent operating area
- 5 Inlet pressure

- 3 Continuous operating area with flushing
- ht Total efficiency
- hv Volumeter efficiency

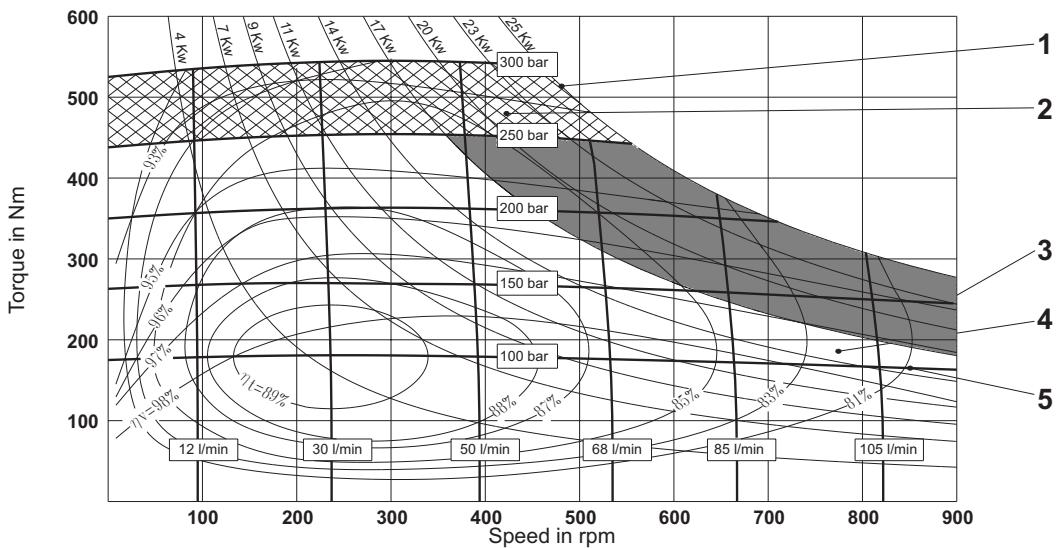
**MR 93**



**MR 110**



**MR 125**



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

## OPERATING DIAGRAM

(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

1 Output power

2 Intermittent operating area

3 Continuous operating area with flushing

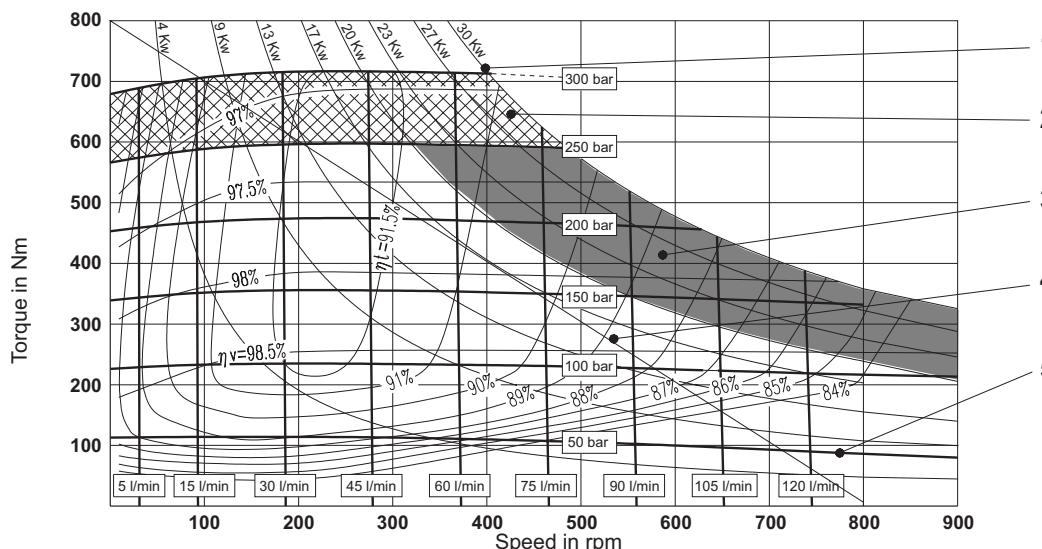
4 Continuous operating area

5 Inlet pressure

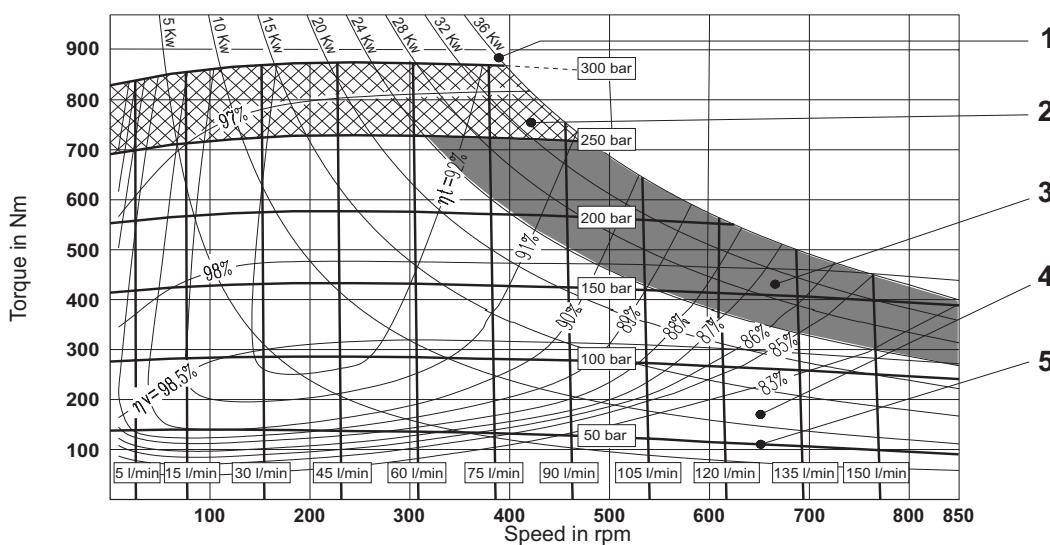
$ht$  Total efficiency

$hv$  Volumeter efficiency

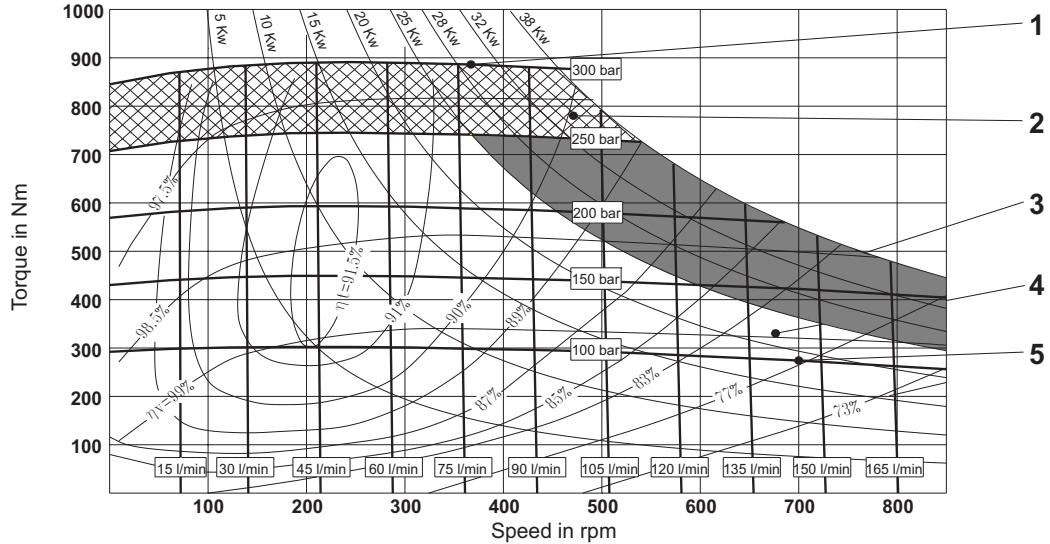
**MR 160**



**MR 190**



**MR 200**



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

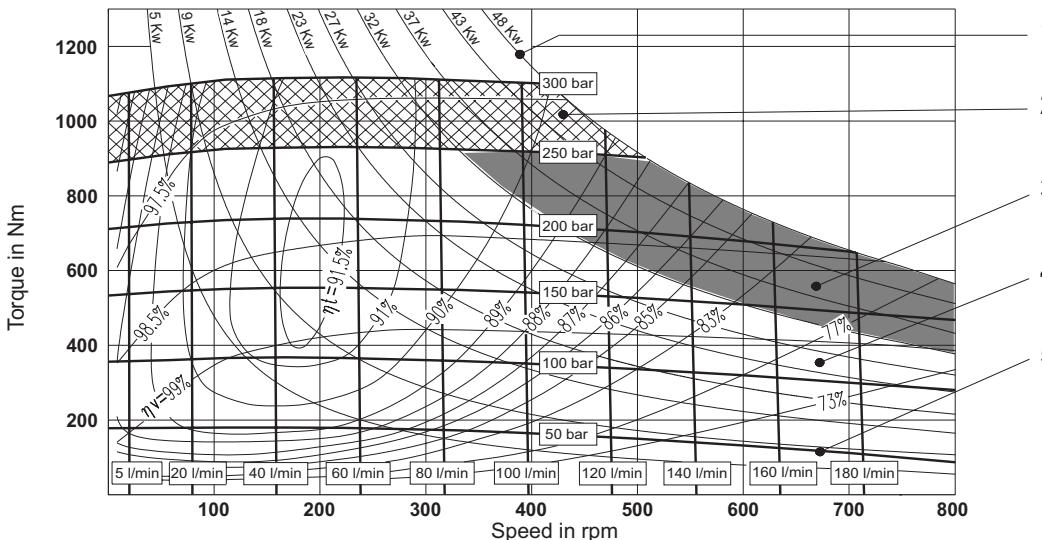
## OPERATING DIAGRAM

(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

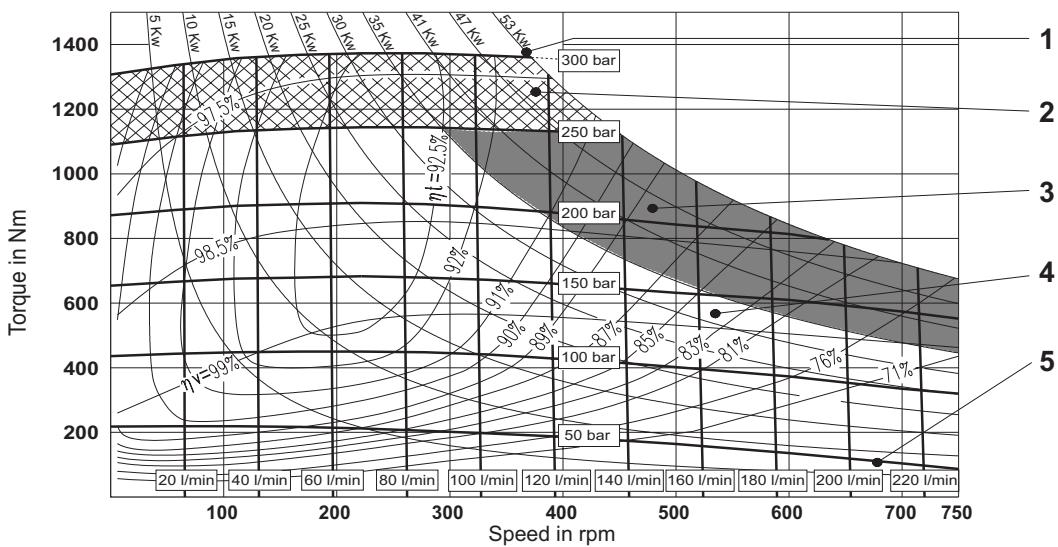
- 1 Output power
- 2 Intermittent operating area
- 4 Continuous operating area

- 3 Continuous operating area with flushing
- 5 Inlet pressure
- $\eta_{\text{t}}$  Total efficiency
- $\eta_{\text{v}}$  Volumeter efficiency

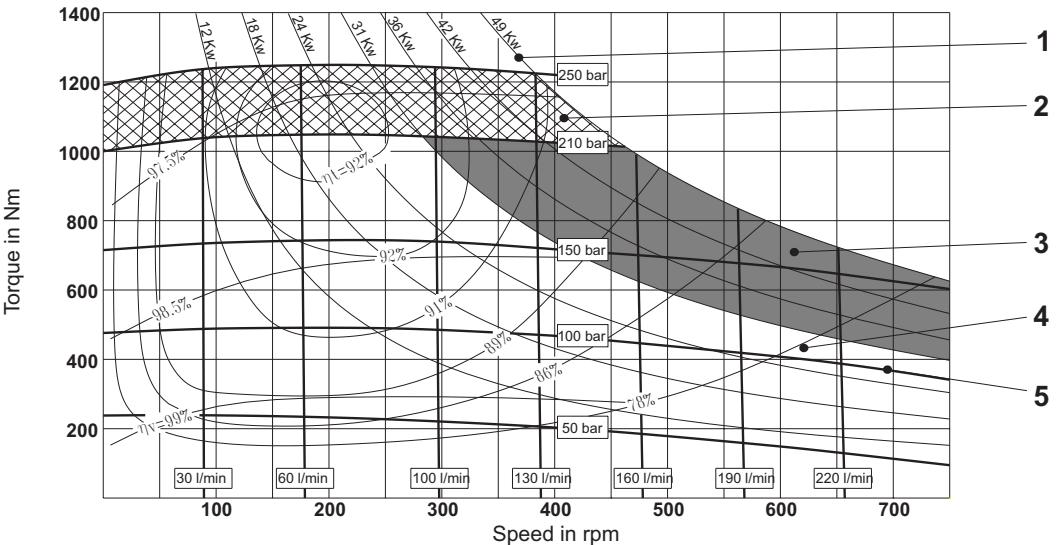
**MR 250**



**MR 300**



**MRE 330**



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

## OPERATING DIAGRAM

(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

**1** Output power

**2** Intermittent operating area

**3** Continuous operating area with flushing

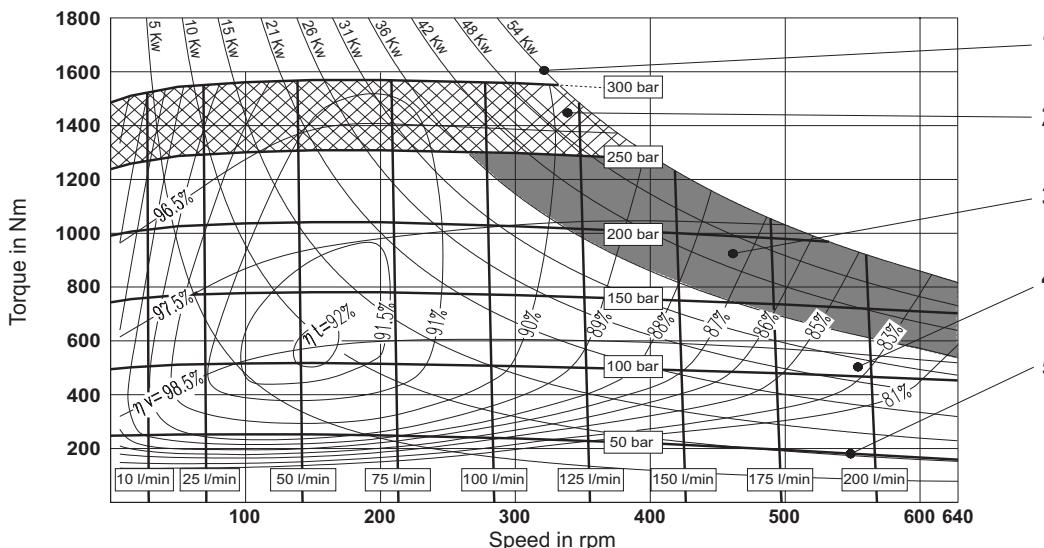
**4** Continuous operating area

**5** Inlet pressure

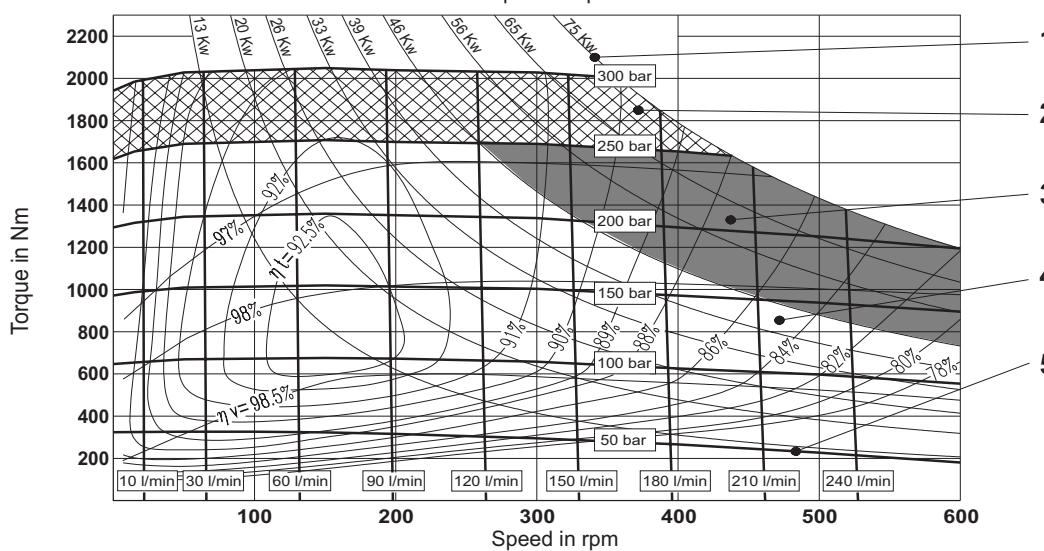
$ht$  Total efficiency

$hv$  Volumeter efficiency

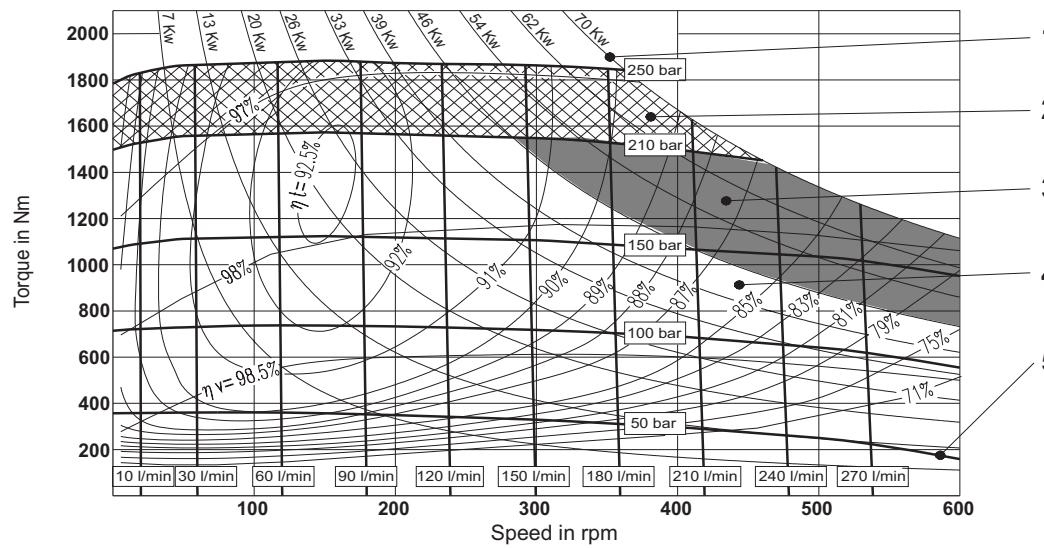
**MR 350**



**MR 450**



**MRE 500**



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

## OPERATING DIAGRAM

(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

**1** Output power

**2** Intermittent operating area

**3** Continuous operating area with flushing

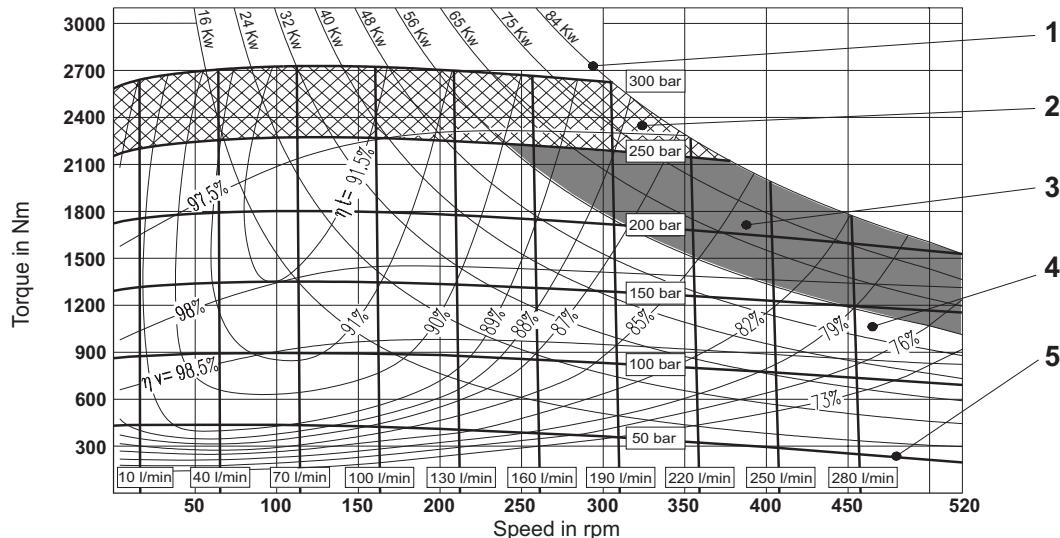
**4** Continuous operating area

**5** Inlet pressure

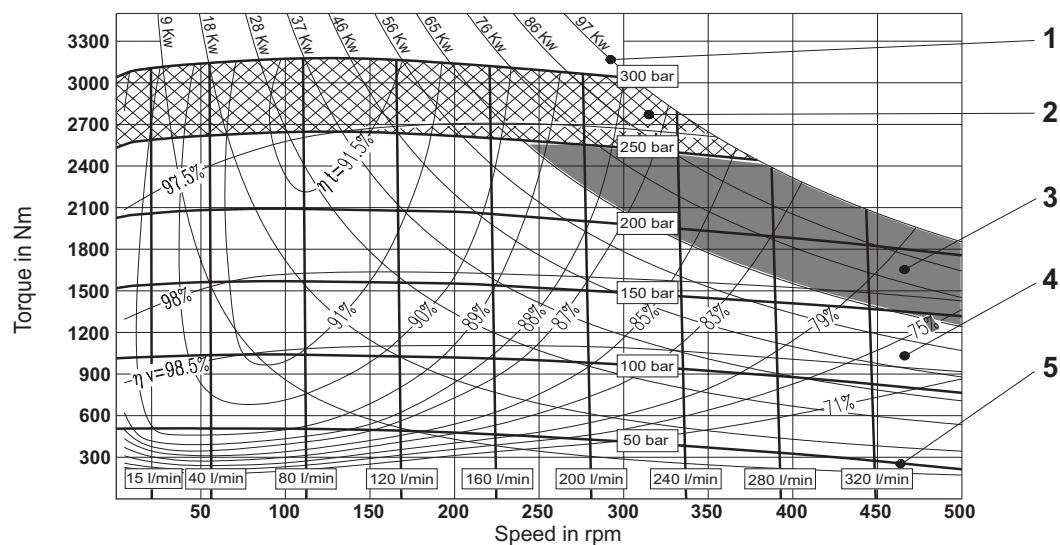
**ht** Total efficiency

**hv** Volumeter efficiency

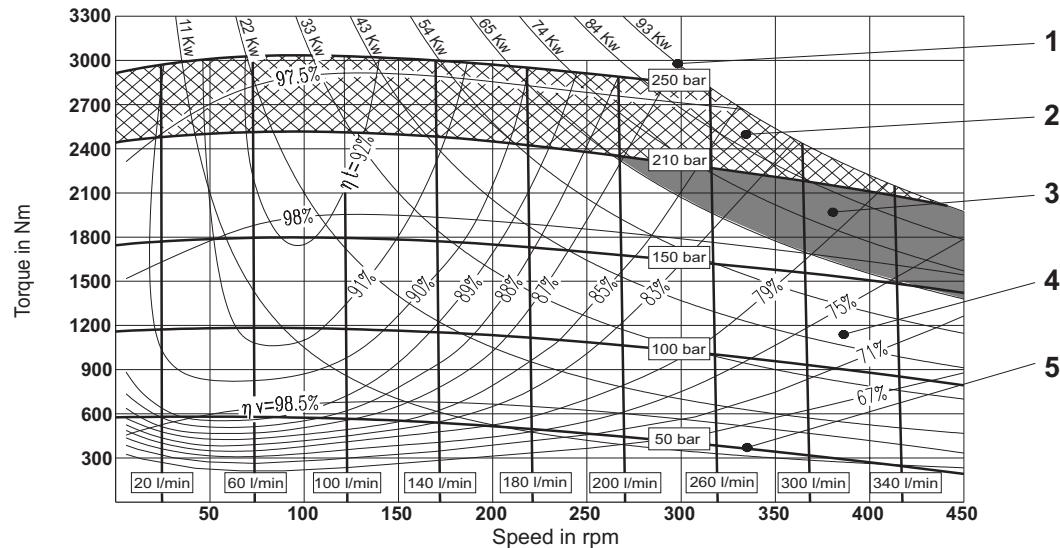
### MR 600



### MR 700



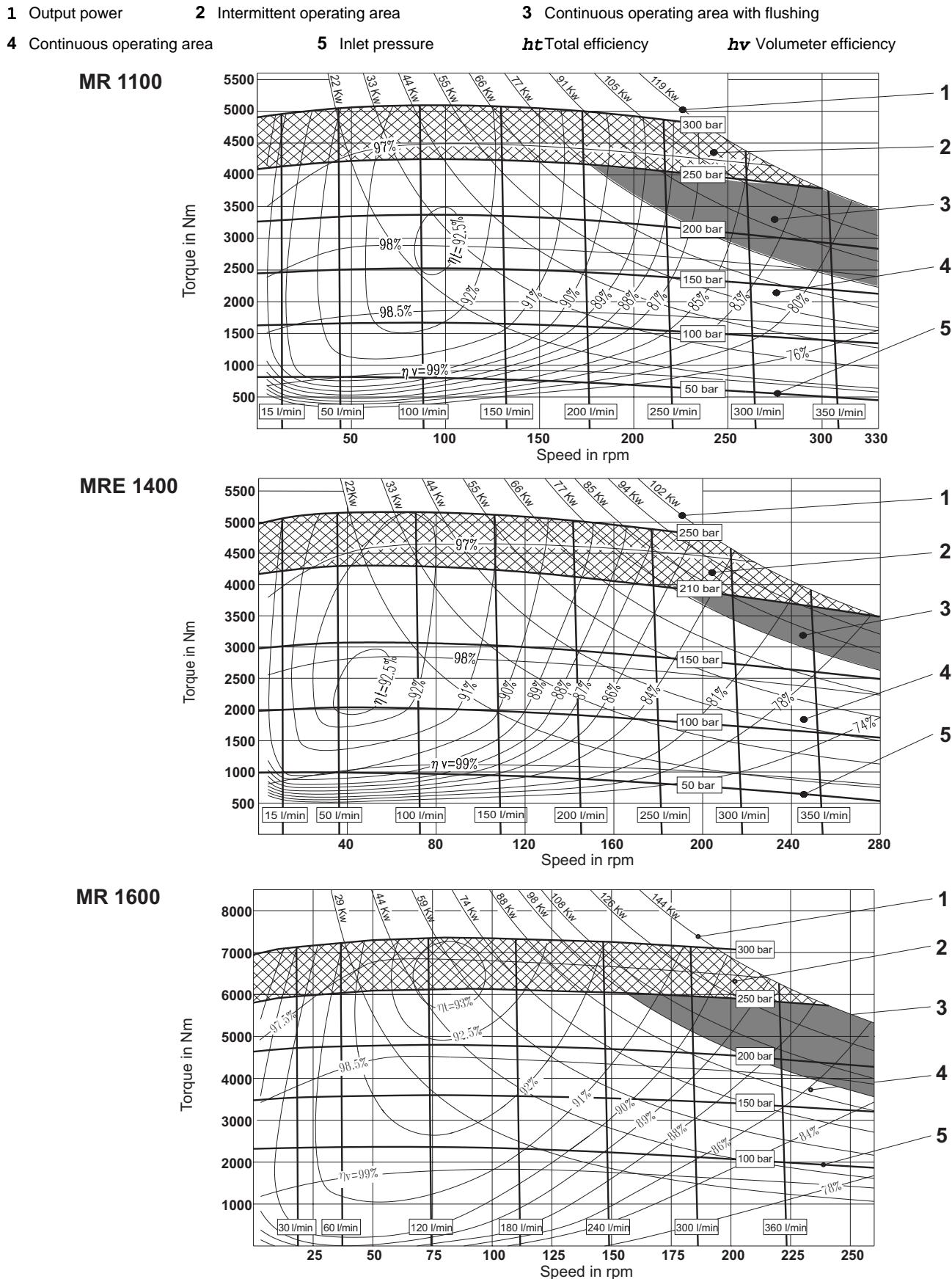
### MRE 800



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

## OPERATING DIAGRAM

(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

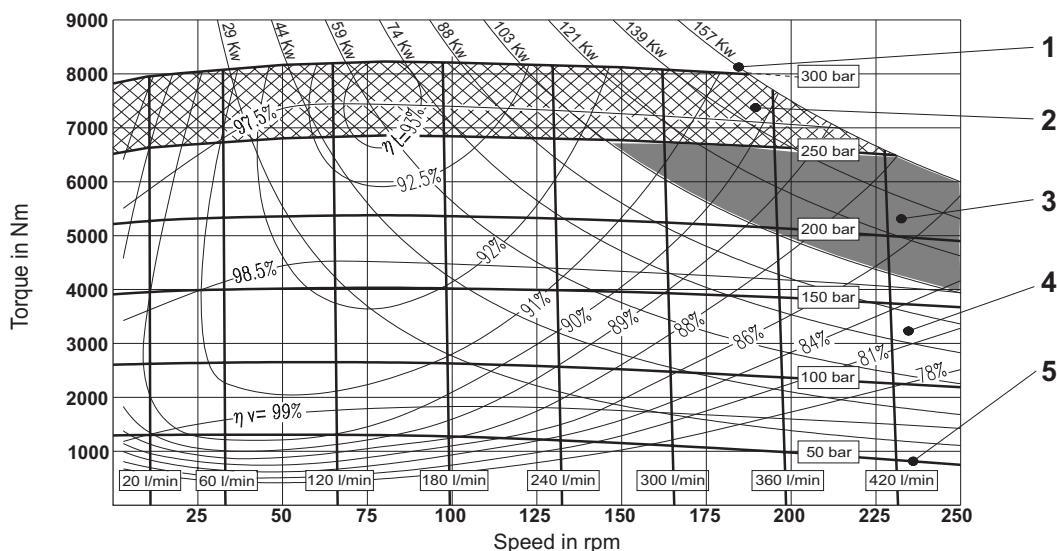
## OPERATING DIAGRAM

(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

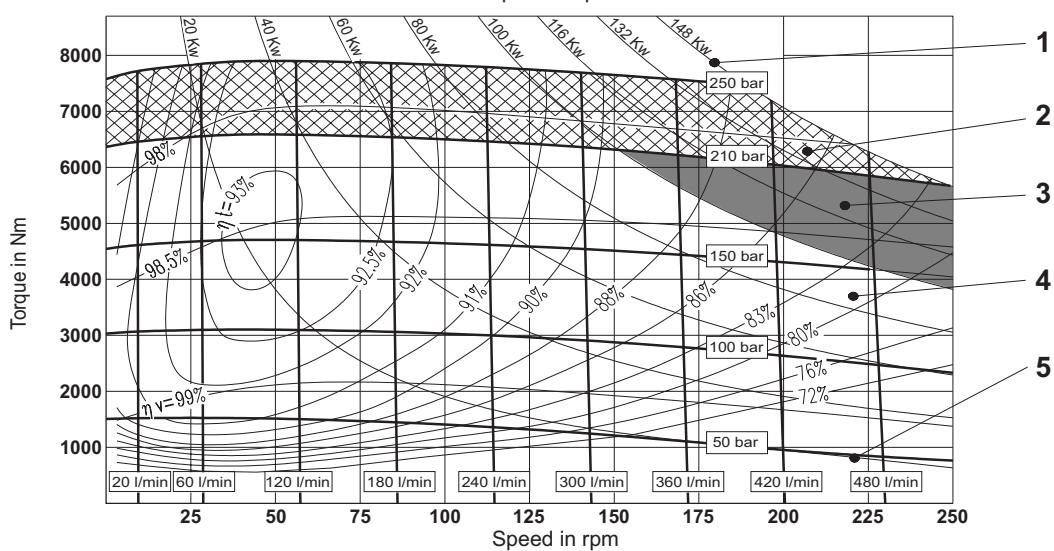
- 1 Output power
- 2 Intermittent operating area
- 4 Continuous operating area

- 3 Continuous operating area with flushing
- 5 Inlet pressure
- $ht$  Total efficiency
- $hv$  Volumeter efficiency

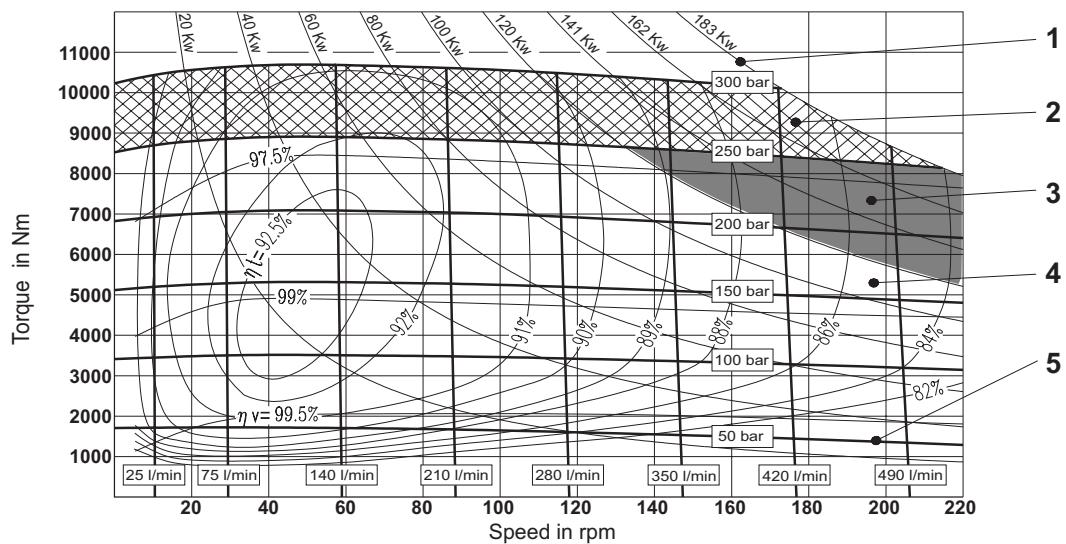
**MR 1800**



**MRE 2100**



**MR 2400**



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

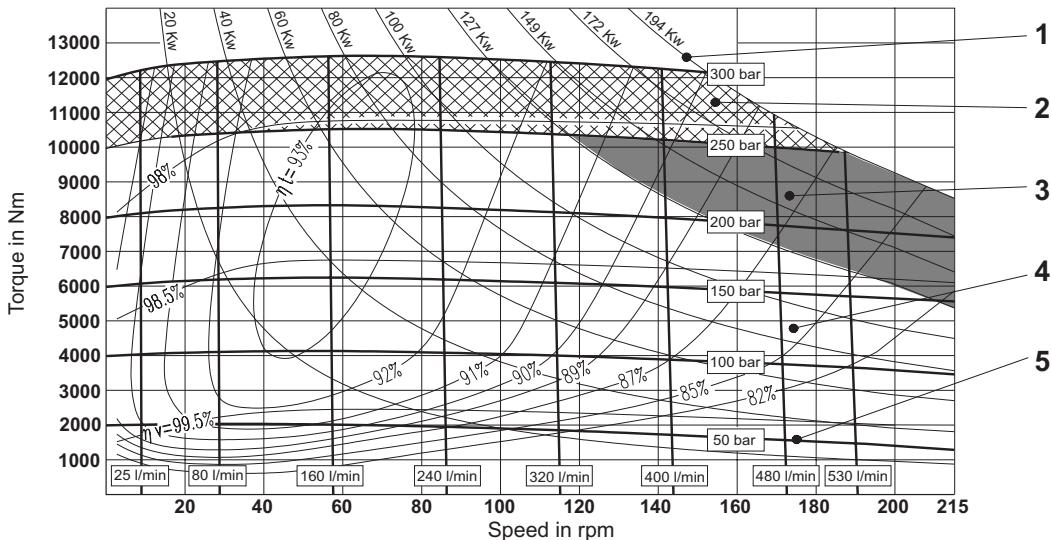
## OPERATING DIAGRAM

(average values) measured at  $\nu = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

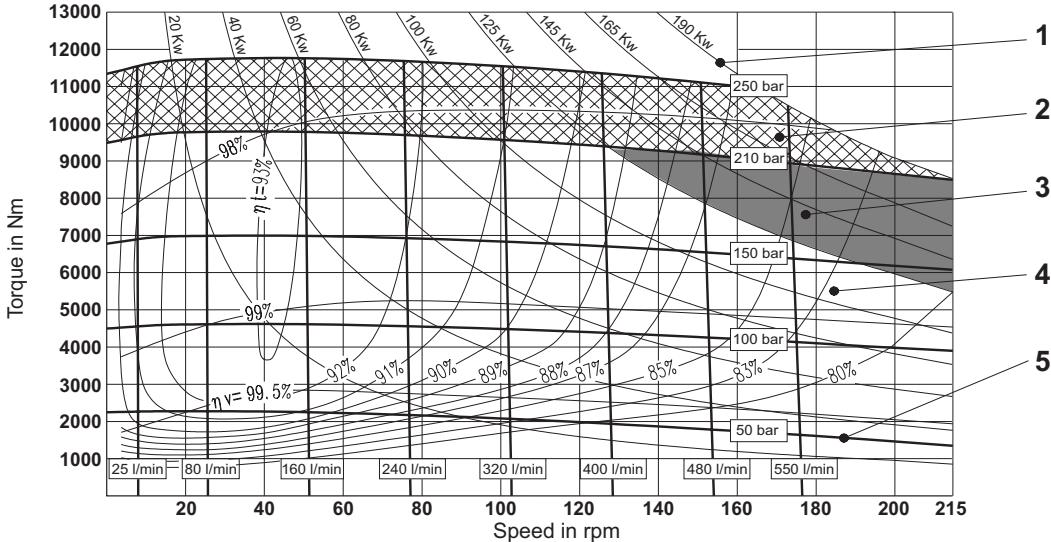
- 1 Output power
- 2 Intermittent operating area
- 4 Continuous operating area

- 3 Continuous operating area with flushing
- 5 Inlet pressure
- $ht$  Total efficiency
- $hv$  Volumeter efficiency

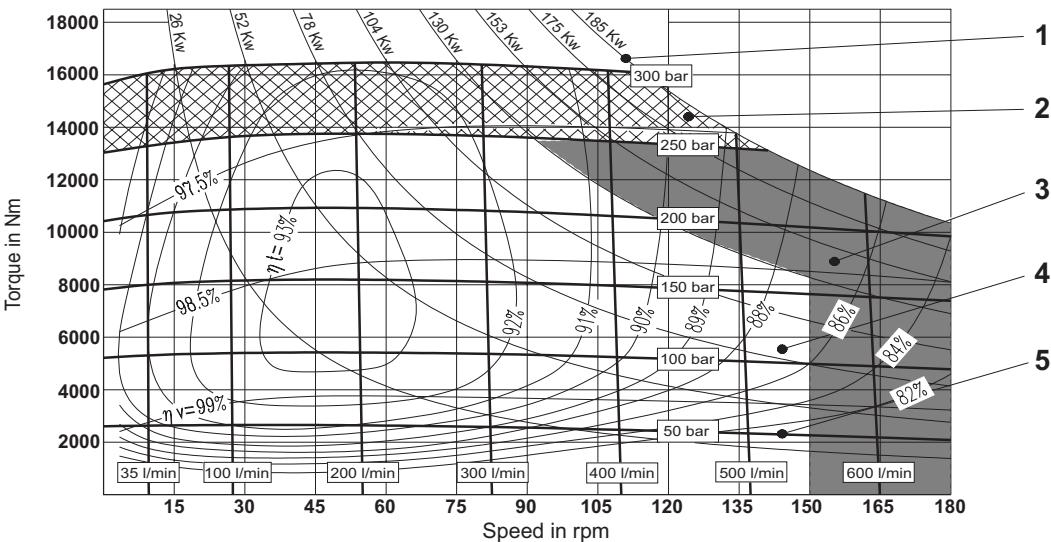
**MR 2800**



**MRE 3100**



**MR 3600**



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

## OPERATING DIAGRAM

(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

1 Output power

2 Intermittent operating area

3 Continuous operating area with flushing

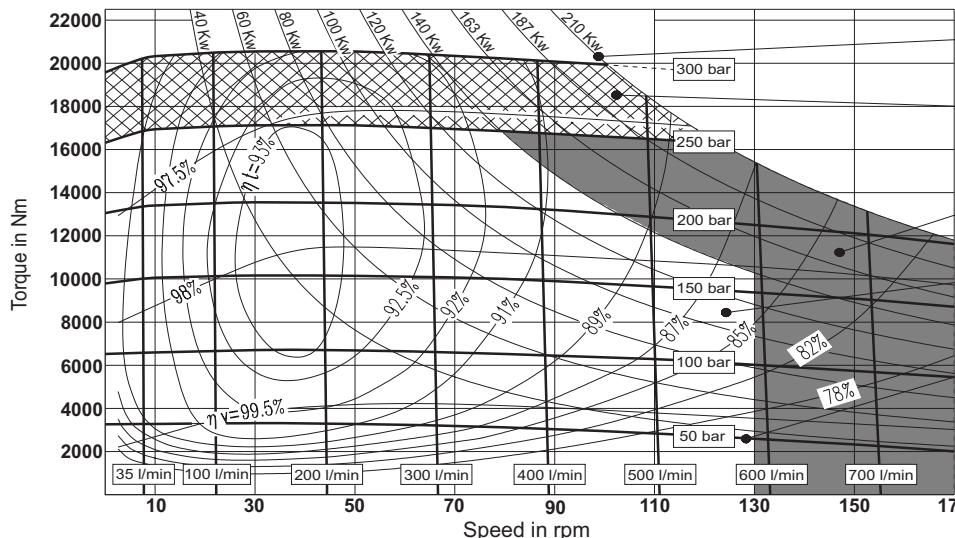
4 Continuous operating area

5 Inlet pressure

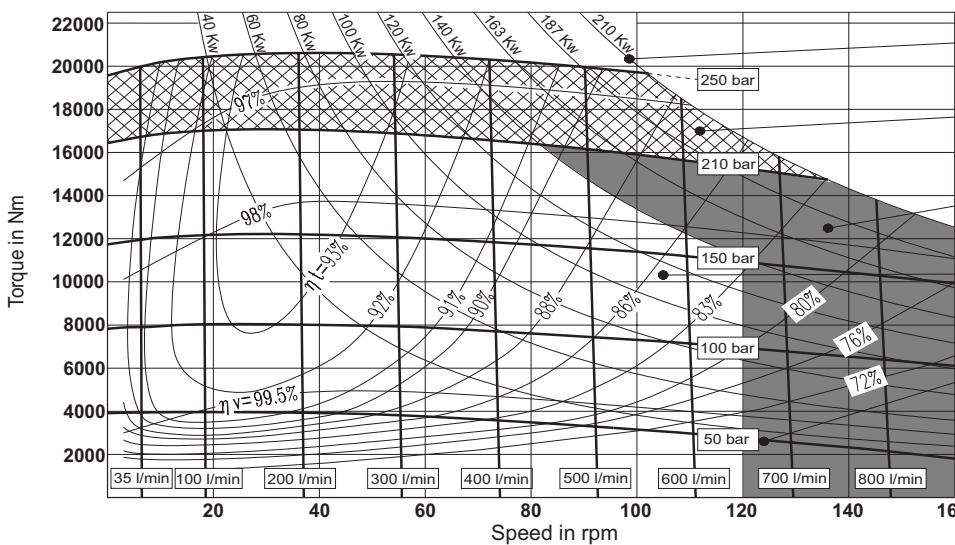
$\eta_{\text{t}}$  Total efficiency

$\eta_{\text{v}}$  Volumeter efficiency

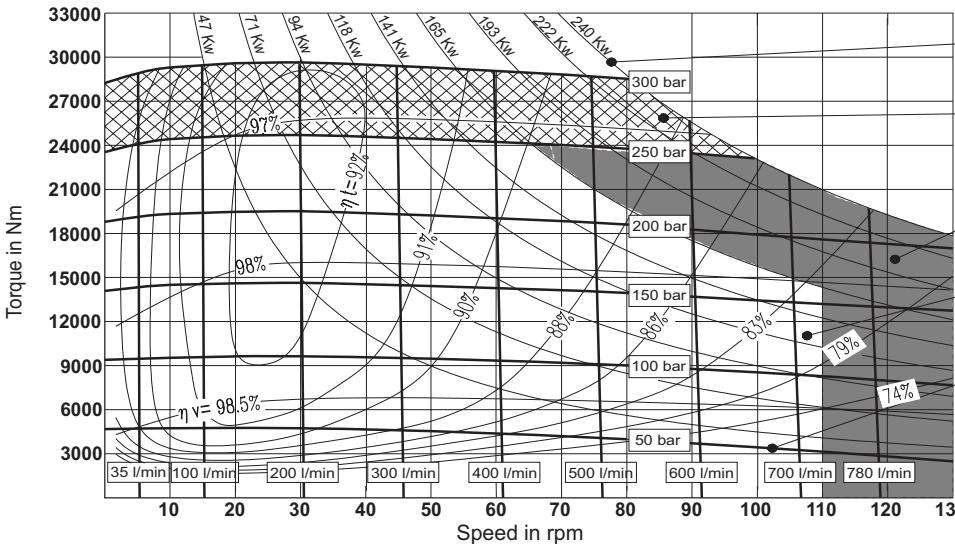
### MR 4500



### MRE 5400



### MR 6500



# OPERATING DIAGRAM - MOTOR TYPE MR - MRE

## OPERATING DIAGRAM

(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

**1** Output power

**2** Intermittent operating area

**3** Continuous operating area with flushing

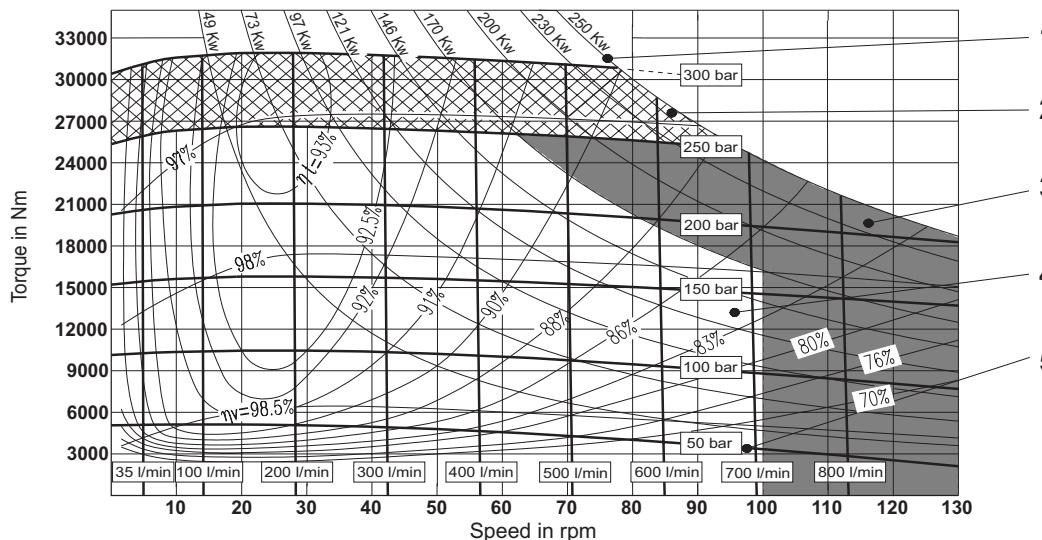
**4** Continuous operating area

**5** Inlet pressure

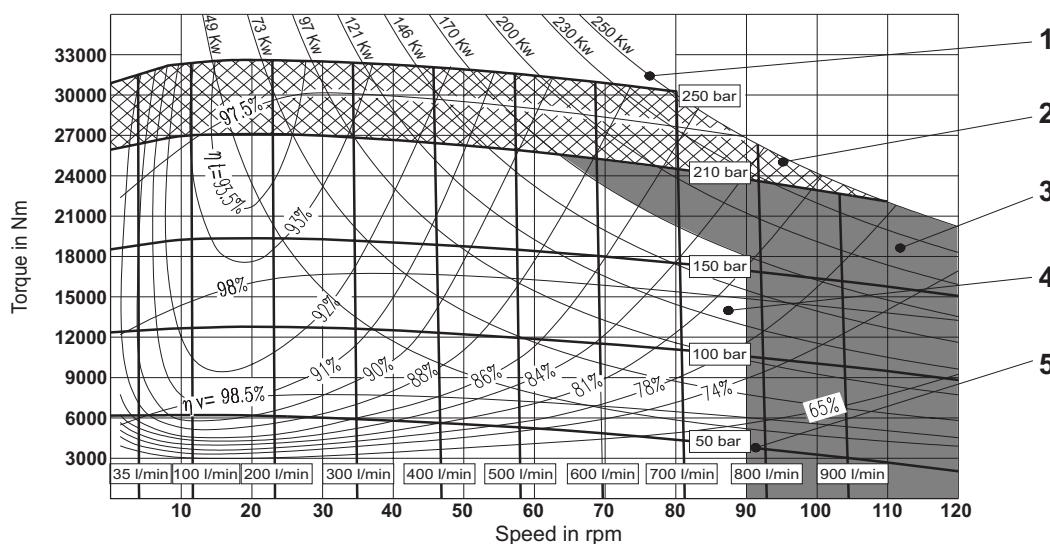
$ht$  Total efficiency

$hv$  Volumeter efficiency

**MR 7000**

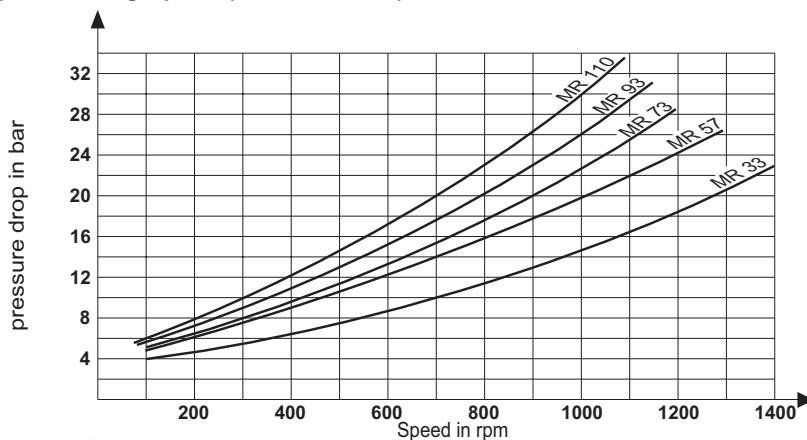


**MRE 8200**

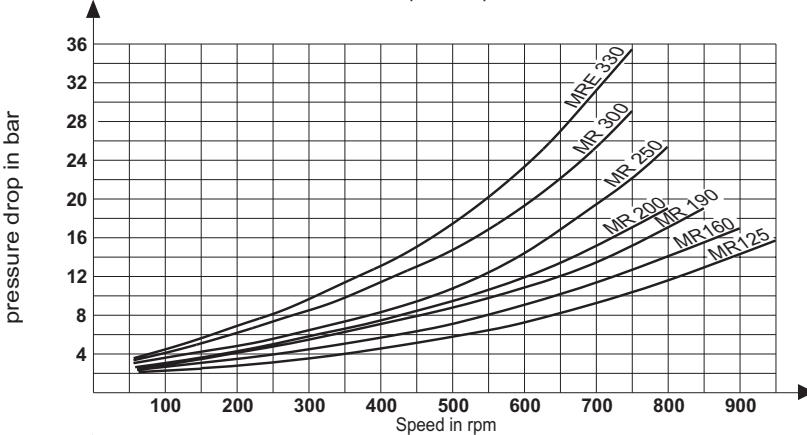


**OPERATING DIAGRAM**(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$ Min. required pressure difference  $\Delta p$  with idling speed (shaft unloaded)

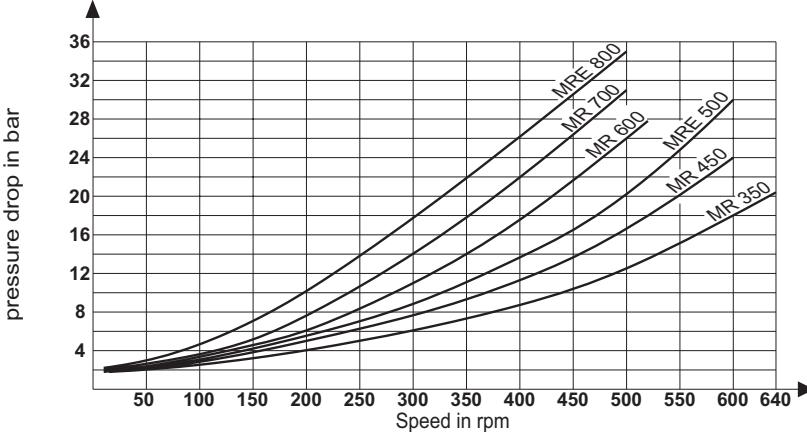
**MR**  
**33 - 110**



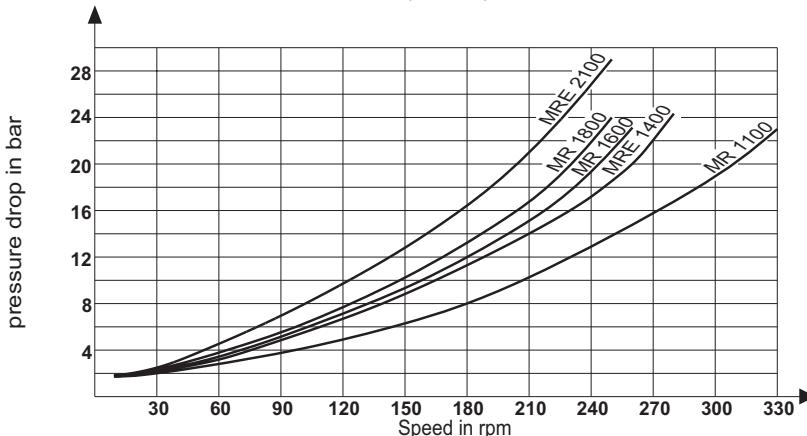
**MR - MRE**  
**125 - 330**



**MR - MRE**  
**350 - 800**

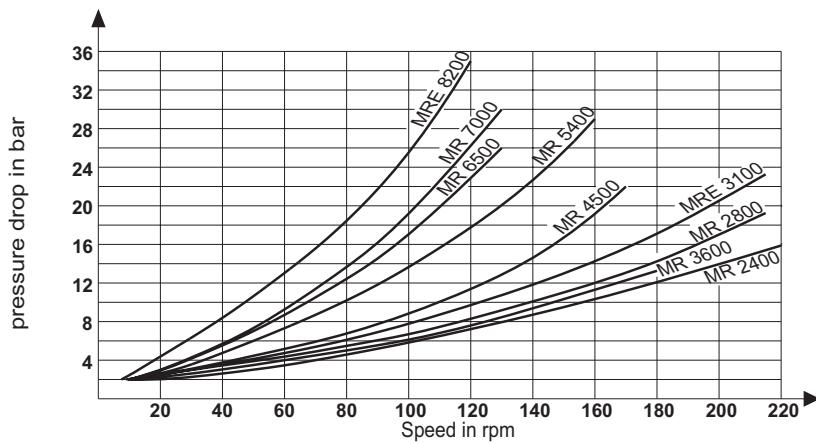


**MR - MRE**  
**1100 - 2100**



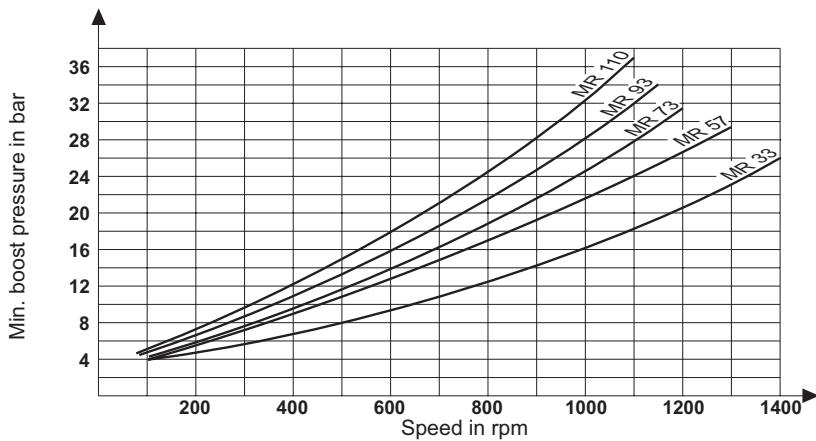
**OPERATINGDIAGRAM**(average values) measured at  $\eta = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$ Min. required pressure difference  $Dp$  with idling speed (shaft unloaded)

**MR - MRE**  
**2400 - 8200**

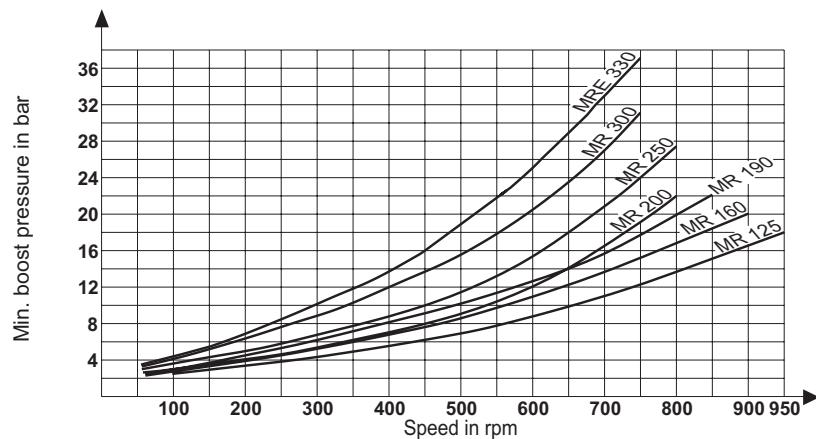


Minimum boost pressure during pump operation

**MR**  
**33 - 110**



**MR - MRE**  
**125 - 330**



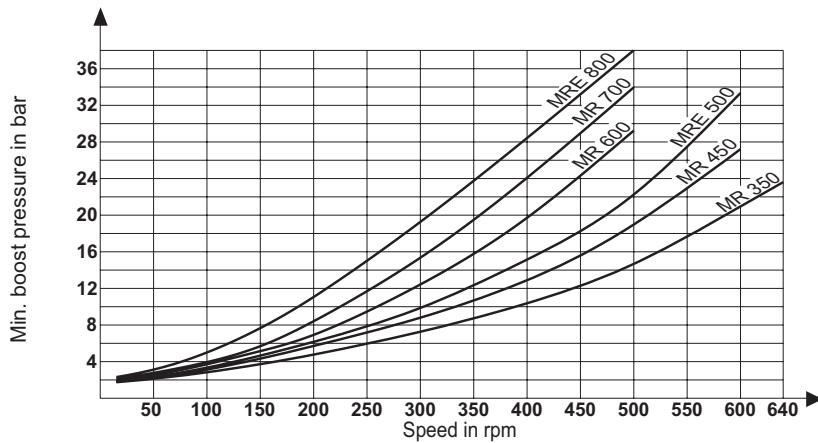
## OPERATING DIAGRAM - MOTOR TYPE MR - MRE

### OPERATING DIAGRAM

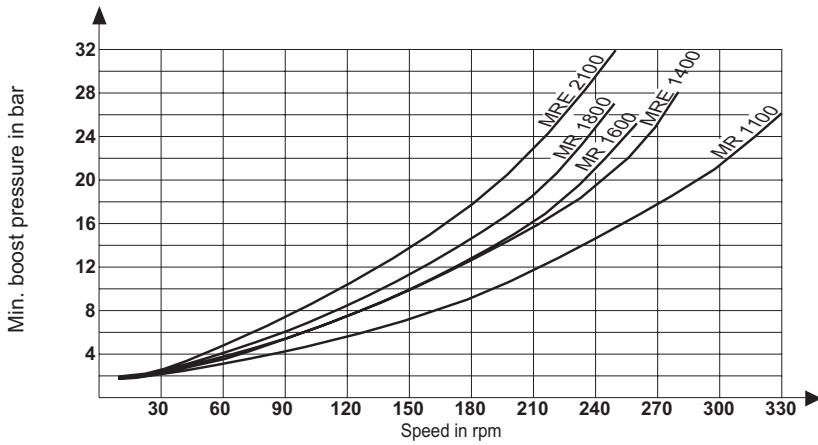
(average values) measured at  $\nu = 36 \text{ mm}^2/\text{s}$ ;  $t = 45^\circ \text{ C}$ ;  $p_{\text{outlet}} = 0 \text{ bar}$

Minimum boost pressure during pump operation

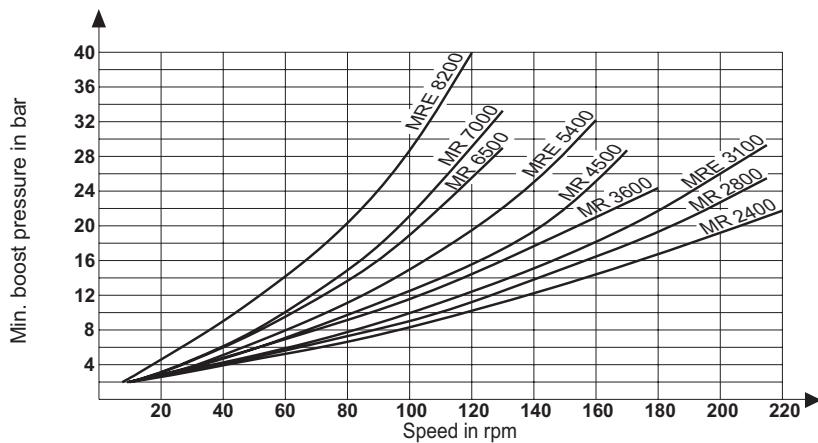
**MR - MRE  
350 - 800**



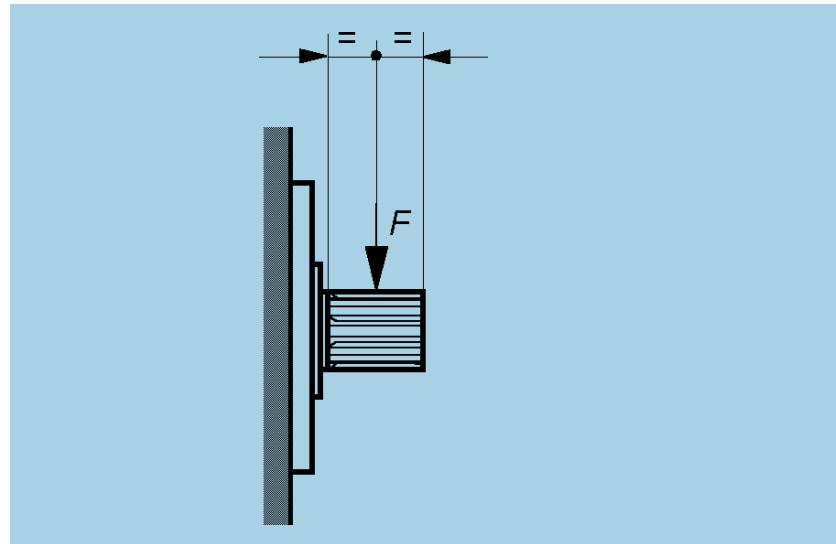
**MR - MRE  
1100 - 2100**



**MR - MRE  
2400 - 8200**



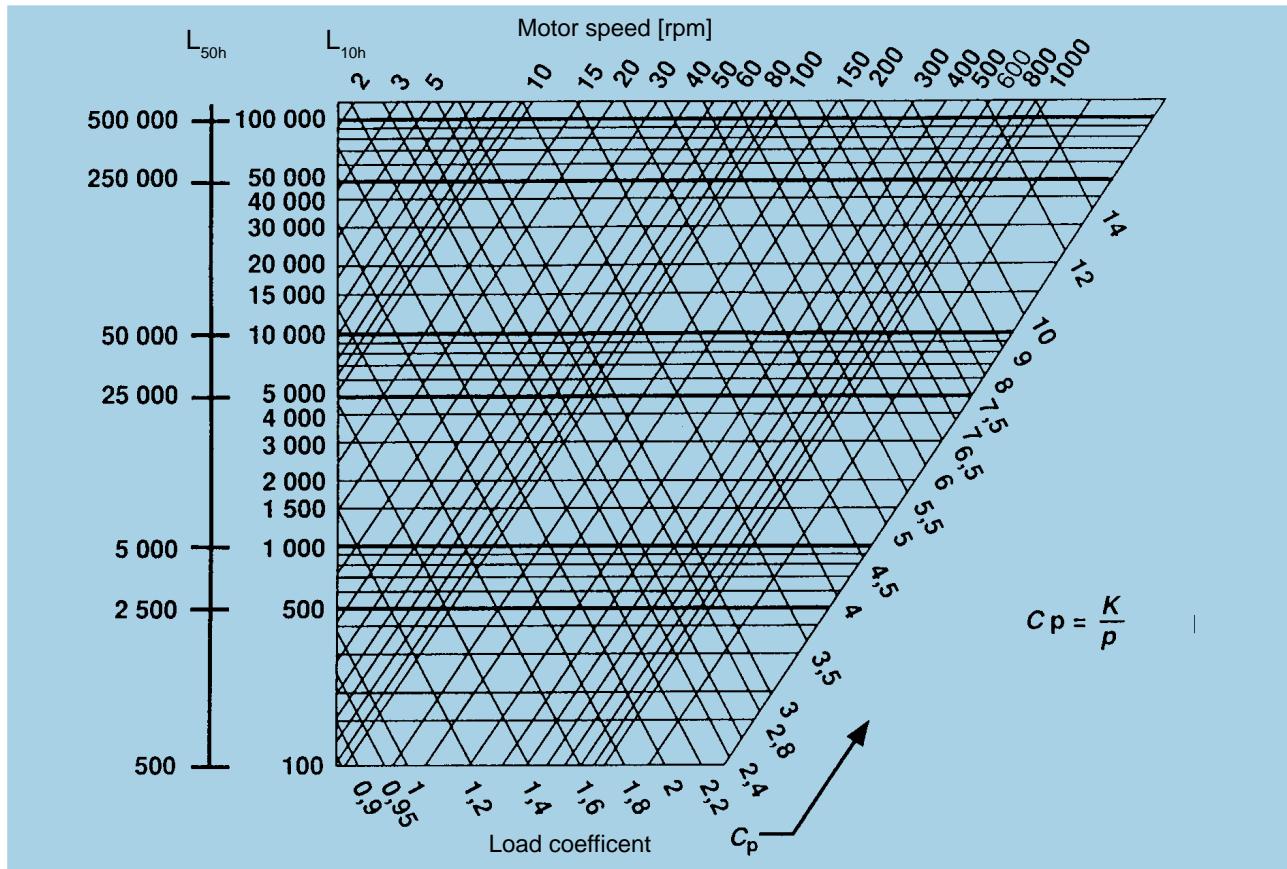
## RADIAL LOAD



MOTOR TYPE	RADIAL FORCE <sub>MAX</sub> I BRIEFLY PERMITTED WITH DYNAMIC LOAD F in kN <sup>1)</sup>	MAX. PERMITTED RADIAL FORCE IN SHAFT CENTRE BASED ON L <sub>H10</sub> 5000 HOURS			speed in rpm
		INPUT PRESSURE 200 bar F in kN	INPUT PRESSURE 150 bar F in kN	INPUT PRESSURE 100 bar F in kN	
<b>MR 33</b>	19,0	9,5	10,2	10,6	400
<b>MR 57</b>	19,0	9,5	10,2	10,6	400
<b>MR 73</b>	22,5	9,0	11,6	13,5	350
<b>MR 93</b>	22,5	9,0	11,6	13,5	350
<b>MR 110</b>	22,5	9,0	11,6	13,5	350
<b>MR 125</b>	22,5	5,0	9,9	12,9	275
<b>MR 160</b>	22,5	5,0	9,9	12,9	275
<b>MR 190</b>	22,5	5,0	9,9	12,9	275
<b>MR 200 *</b>	-	-	-	-	-
<b>MR 250</b>	28,0	5,6	9,9	12,6	250
<b>MR 300</b>	28,0	5,6	9,9	12,6	250
<b>MR 350</b>	35,0	14,5	18,4	21,2	225
<b>MR 450</b>	35,0	14,5	18,4	21,2	225
<b>MR 600</b>	43,0	15,0	22,5	27,3	200
<b>MR 700</b>	43,0	15,0	22,5	27,3	200
<b>MR 1100</b>	54,0	18,5	28,5	35,2	150
<b>MR 1600</b>	68,0	26,2	40,6	50,0	125
<b>MR 1800</b>	68,0	26,2	40,6	50,0	125
<b>MR 2400</b>	85,0	50,1	66,0	76,8	110
<b>MR 2800</b>	85,0	54,0	69,0	79,4	100
<b>MR 3600</b>	108,0	55,0	90,0	103,0	100
<b>MR 4500</b>	108,0	78,0	97,0	109,0	85
<b>MR 6500</b>	134,0	74,0	123,0	141,0	50
<b>MR 7000</b>	134,0	74,0	123,0	141,0	50
<b>MRE 330</b>	28,0	4,5	8,5	11,9	250
<b>MRE 500</b>	35,0	12,4	17,3	20,8	225
<b>MRE 800</b>	43,0	8,5	19,8	26,3	200
<b>MRE 1400</b>	54,0	8,6	24,0	33,6	140
<b>MRE 2100</b>	68,0	12,5	35,6	48,3	120
<b>MRE 3100</b>	85,0	45,0	64,5	77,6	100
<b>MRE 5400</b>	108,0	63,0	90,2	107,3	80
<b>MRE 8200</b>	134,0	68,0	110,0	128,0	50

<sup>1)</sup> in accordance with the dynamic condition, higher values can be accepted - MR 200\* only code "F1"

## BEARING LIFE

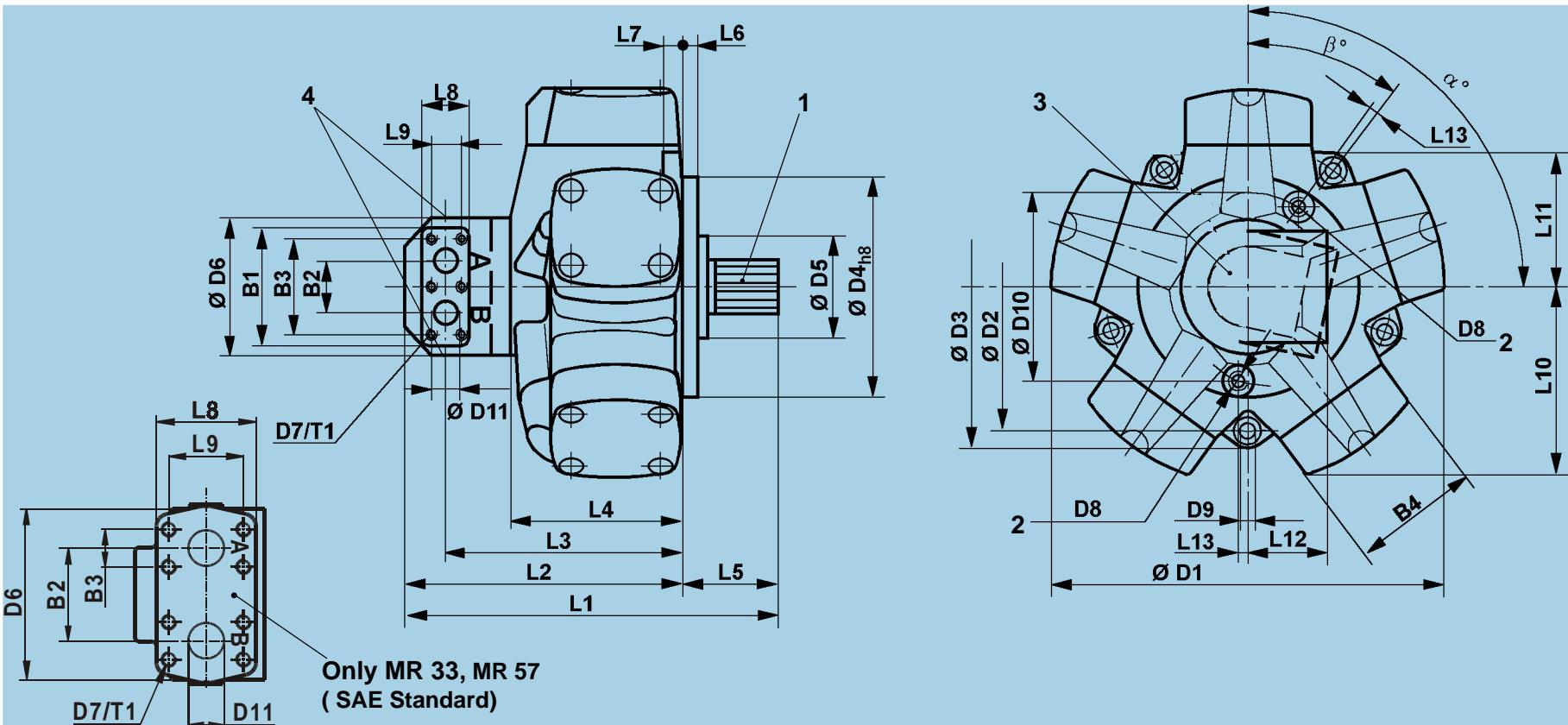


$C_p$  = Load coefficient  
 $K$  = Service life coefficient for standard bearing  
 $p$  = operating pressure in bar

$L_{10h}$  is the theoretically service life value normally reached or exceeded by the 90% of the bearings.

50 % of the bearings reach the value  $L_{50h} = 5$  times  $L_{10h}$ .

MOTOR TYPE	K	MOTOR TYPE	K	MOTOR TYPE	K
<b>MR 33</b>	2150	<b>MRE 330</b>	850	<b>MRE 2100</b>	722
<b>MR 57</b>	2150	<b>MR 350</b>	1126	<b>MR 2400</b>	924
<b>MR 73</b>	1320	<b>MR 450</b>	1126	<b>MR 2800</b>	924
<b>MR 93</b>	1320	<b>MRE 500</b>	1021	<b>MRE 3100</b>	828
<b>MR 110</b>	1320	<b>MR 600</b>	920	<b>MR 3600</b>	709
<b>MR 125</b>	950	<b>MR 700</b>	920	<b>MR 4500</b>	709
<b>MR 160</b>	950	<b>MRE 800</b>	808	<b>MRE 5400</b>	591
<b>MR 190</b>	950	<b>MR 1100</b>	844	<b>MR 6500</b>	710
<b>MR 200</b>	950	<b>MRE 1400</b>	693	<b>MR 7000</b>	710
<b>MR 250</b>	950	<b>MR 1600</b>	835	<b>MRE 8200</b>	550
<b>MR 300</b>	950	<b>MR 1800</b>	835		

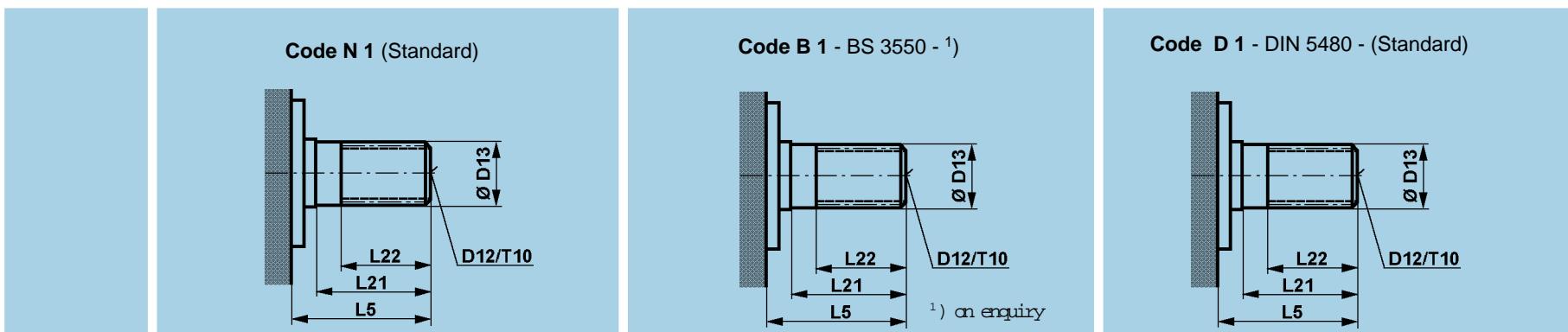


- 1 Splined shaft with flank contact  
(for dimension see page 26)  
Ordering code "N1"  
(for further shaft ends see page 26 - 27)
- 2 Case drain port  
BSP threads to ISO 228/1
- 3 On request the port flange can be rotated by 72°  
(For MR 33, MR 57, MR 73, MR 93, MR 110, MR 125, MR 160, MR 190, MR 200, MR 250, MR 300, MRE 330, MR 350, MR 450, MRE 500, MR 600, MR 700, MRE 800 can be rotated by 36°)  
For standard position see angle  $\alpha$ .
- 4 Port 1/4" BSP threads to ISO 228/1  
for pressure reading.

Dir. of Rotation (Viewed on shaft end)	Port inlet	ordering code (see page 35)
clockwise	A	"N"
anti-clockwise	B	
clockwise	B	
anti-clockwise	A	"S"

## MOTOR DIMENSIONS - MOTOR TYPE MR - MRE

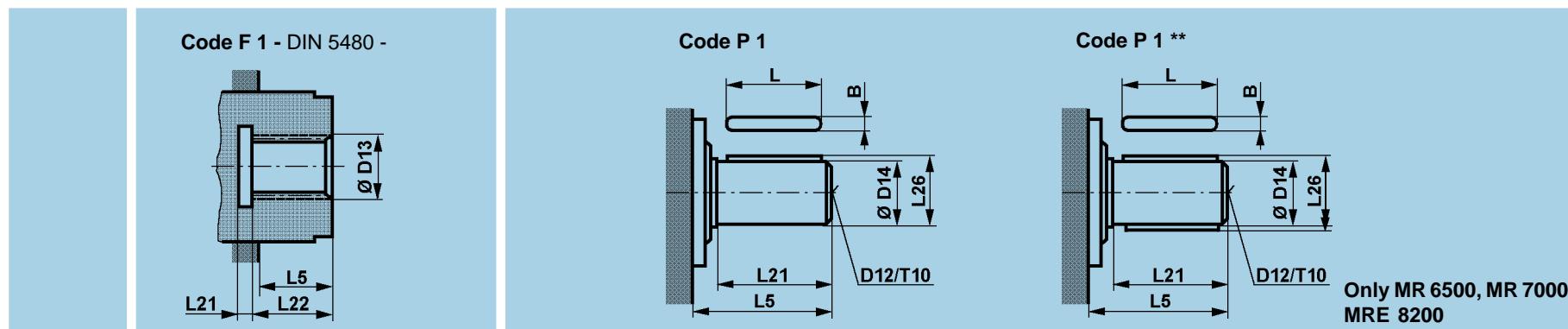
MOTOR TYPE	L1	L2	L3	L4	L5	L6	L7	L8	L9	L10	L11	L12	L13	B1	B2	B3	B4	Ø D1	Ø D2	Ø D3	Ø D4 <sub>h8</sub> *	Ø D5	Ø D6	D7	T1	D8	D9	Ø D10	Ø D11	α	β
<b>MR 33 MR 57</b>	253,2	196	148	107	57,2	14	19	70	52,4	110,2	78,5	70	19,7	124	65	26,2	69,4	235,4	160	180	125	-	120	M10	25	G1/4	9	97	25	108°	36°
<b>MR 73 MR 93 MR 110</b>	297	228,5	190,5	131,5	68,5	17	20	54	34	119,8	94	72	-	120	50	100	90	250	204	224,4	145	-	129	M8	15	G3/8	11	-	20	90°	36°
<b>MR 125 MR 160 MR 190</b>	309	242	204	145	67	14	16	54	34	147,5	103	72	6,5	120	50	100	100	313,2	225	249	160	-	129	M8	15	G 3/8	11	160	20	90°	36°
<b>MR 200 MR 250 MR 300 MRE 330</b>	323	242	204	145	81	15	16	54	34	153,5	119	72	7,5	120	50	100	100	328	232	256	175	90	129	M8	15	G 3/8	11	162	20	90°	36°
<b>MR 350 MR 450 MRE 500</b>	376	279	235	167	97	15	18	70,4	40	174,5	130	84	9,5	142	60	120	119	368	266	296	190	96	156	M10	18	G 3/8	13	194	25	90°	36°
<b>MR 600 MR 700 MRE 800</b>	400	299	255	187	101	15	20	70,4	40	192	143	84	8	142	60	120	133	405	290	320	220	102	156	M10	18	G 3/8	13	207	25	90°	36°
<b>MR 1100 MRE 1400</b>	458	341	293	203	117	20	22	82	50	223	165	105	9	162	73	136	148	470	330	367	250	120	172	M12	21	G 1/2	15	228	31	104°	36°
<b>MR 1600 MR 1800 MRE 2100</b>	506	374	326	236	132	21	24	82	50	264	197	105	11	162	73	136	168	558	380	423	290	148	172	M12	21	G 1/2	17	266	31	90°	36°
<b>MR 2400 MR 2800 MRE 3100</b>	619	466	392	285	153	24	26	98	62	303	221	123	15	208	86	180	190	642	440	494	335	140	215	M14	28	G 1/2	19	314	37	90°	36°
<b>MR 3600 MR 4500 MRE 5400</b>	699,5	489,5	418,5	307,5	210	34	28	98	68	359,5	247	140	19	230	116	200	240	766	540	597	400 *D4 <sub>h7</sub>	-	215	M16	32	G 1/2	23	380	38	108°	36°
<b>MR 6500 MR 7000 MRE 8200</b>	796	566	495	384	230	37	30	98	68	407,3	247	140	21	230	116	200	264	864	600	658,6	450 *D4 <sub>h7</sub>	190	215	M16	32	G 1/2	25	450	38	108°	36°



Version	N						B						D					
	L5	L21	L22	D12	T10	ØD13	L5	L21	L22	D12	T10	ØD13	L5	L21	L22	D12	T10	ØD13
TYPE																		
MR 33	57	40	28	-	-	B6x26x32	-	-	-	-	-	-	57	40	28	-	-	W32x1,5x20-8e
MR 57																		
MR 73	68,5	51,5	31,5	M12	-	B6x28x34	-	-	-	-	-	-	68,5	51,5	31,5	M12	-	W35x2x16-8e
MR 93																		
MR 110																		
MR 125	67	50	35,5	M12	20	B8x32x38	67	50	35,5	M12	20	12/24-17	67	50	35,5	M12	20	W38x2x18-8e
MR 160																		
MR 190																		
MR 200 *	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
MR 250																		
MR 300	81	60	46	M12	25	B8x42x48	81	60	45	M12	25	12/24-21	81	60	46	M12	25	W48x2x22-8e
MRE 330																		
MR 350	97	74	56,5	M12	25	B8x46x54	97	74	61	M12	25	8/16-17	97	74	60	M12	25	W55x3x17-8e
MR 450																		
MRE 500																		
MR 600	101	78	62	M12	25	B8x52x60	101	78	62	M12	25	8/16-17	101	78	62	M12	25	W60x3x18-8e
MR 700																		
MRE 800																		
MR 1100	117	88	69	M12	25	B8x62x72	117	88	67	M12	25	6/12-14	117	88	72	M12	25	W70x3x22-8e
MRE 1400																		
MR 1600	132	100	79	M12	25	B10x72x82	132	100	76	M12	25	6/12-20	132	100	80	M12	25	W80x3x25-8e
MR 1800																		
MRE 2100																		
MR 2400	153	120	99	M12	25	B10x82x92	153	120	76	M12	25	6/12-20	153	120	100	M12	25	W90x4x21-8e
MR 2800																		
MRE 3100																		
MR 3600	210	173	144	M12	25	B10x102x112	210	173	142,5	M12	25	6/12-20	210	173	144	M12	25	W110x4x26-8e
MR 4500																		
MRE 5400																		
MR 6500	230	188	150	M12	25	B10x112x125	230	188	153	M12	25	6/12-26	230	188	153	M12	25	W120x4x28-8e
MR 7000																		
MRE 8200																		

NOTE: the threaded holes (D12/T10) for the shaft versions "N1", "B1" and "D1" must be considered as service holes. In case the holes dimensions required by the application are different from the ones listed here above, please contact DENISON Calzoni.

MR 200 \* only code "F1"



Version	F				P									Transmitted torque (Nm)
	Type	L5	L21	L22	ØD13 DIN 5480	L5	L21	L26	D12	T10	ØD14	Key L x B		
MR 33 MR 57	17	5	21	N28x1,25x21-9H	-	-	-	-	-	-	-	-	-	
MR 73 MR 93 MR 110	17	5	26	N32x2x14-9H	-	-	-	-	-	-	-	-	-	
MR 125 MR 160 MR 190	14	5	28	N35x2x16-9H	67	50	43	M12	20	40 k6	45 x 12	496		
MR 200 *	27	5	36	N40x2x18-9H	-	-	-	-	-	-	-	-	-	
MR 250 MR 300 MRE330	27	5	36	N40x2x18-9H	81	60	53,5	M12	25	50 k6	56 x 14	897		
MR 350 MR 450 MRE 500	28	5	38	N47x2x22-9H	97	74	59	M12	25	55 k6	70 x 16	1413		
MR 600 MR 700 MRE 800	28	5	44	N55x3x17-9H	101	78	64	M12	25	60 k6	70 x 18	2030		
MR 1100 MRE 1400	38	8	50	N65x3x20-9H	117	88	76,5	M12	25	70 k6	80 x 20	2690		
MR 1600 MR 1800 MRE 2100	47	8	57	N75x3x24-9H	132	100	85	M12	25	80 k6	90 x 22	4020		
MR 2400 MR 2800 MRE 3100	48	8	62	N85x3x27-9H	153	120	95	M12	25	90 k6	110 x 25	6207		
MR 3600 MR 4500 MRE 5400	50	14	68	N100x3x32-9H	210	173	116	M12	25	110 k6	160 x 28	10757		
MR 6500 MR 7000 MRE 8200	50	14	76	N110x3x35-9H	230	188	138 **	M12	25	124 b8	N°2-180 x 32	28270		

**NOTE**  
For higher values of the torque to be transmitted, please consult DENISON Calzoni

NOTE: the threaded holes (D12/T10) for the shaft versions "P1" must be considered as service holes. In case the holes dimensions required by the application are different from the ones listed here above, please contact DENISON Calzoni.

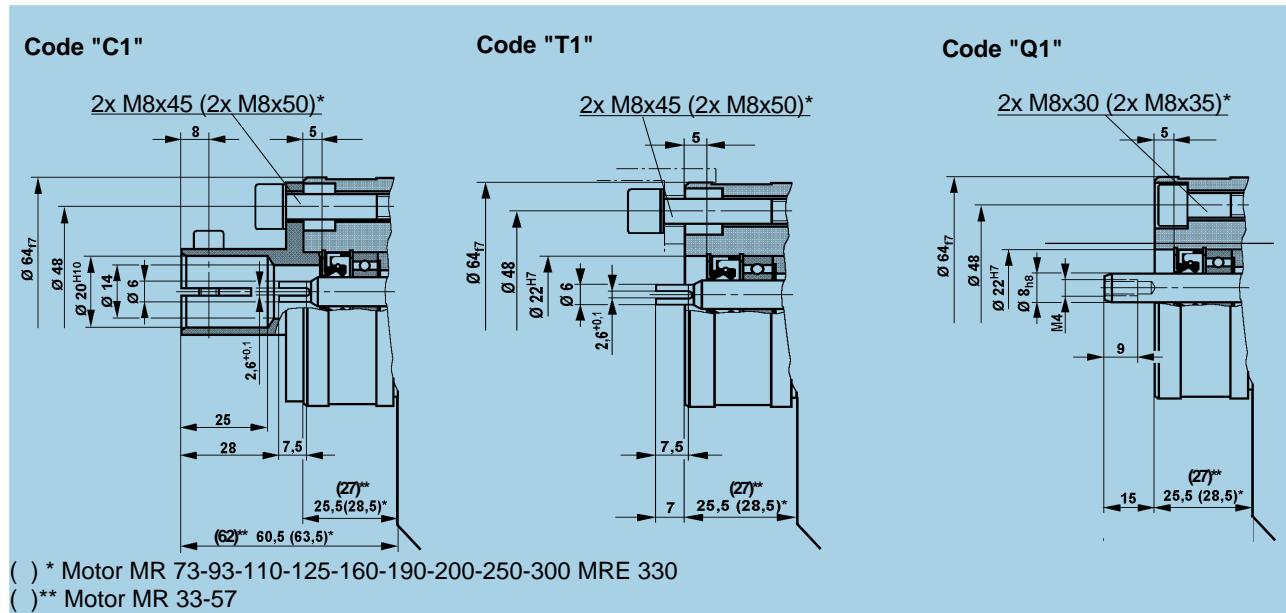
MR 200 \* only code "F1"

\*\*This dimension includes two keys

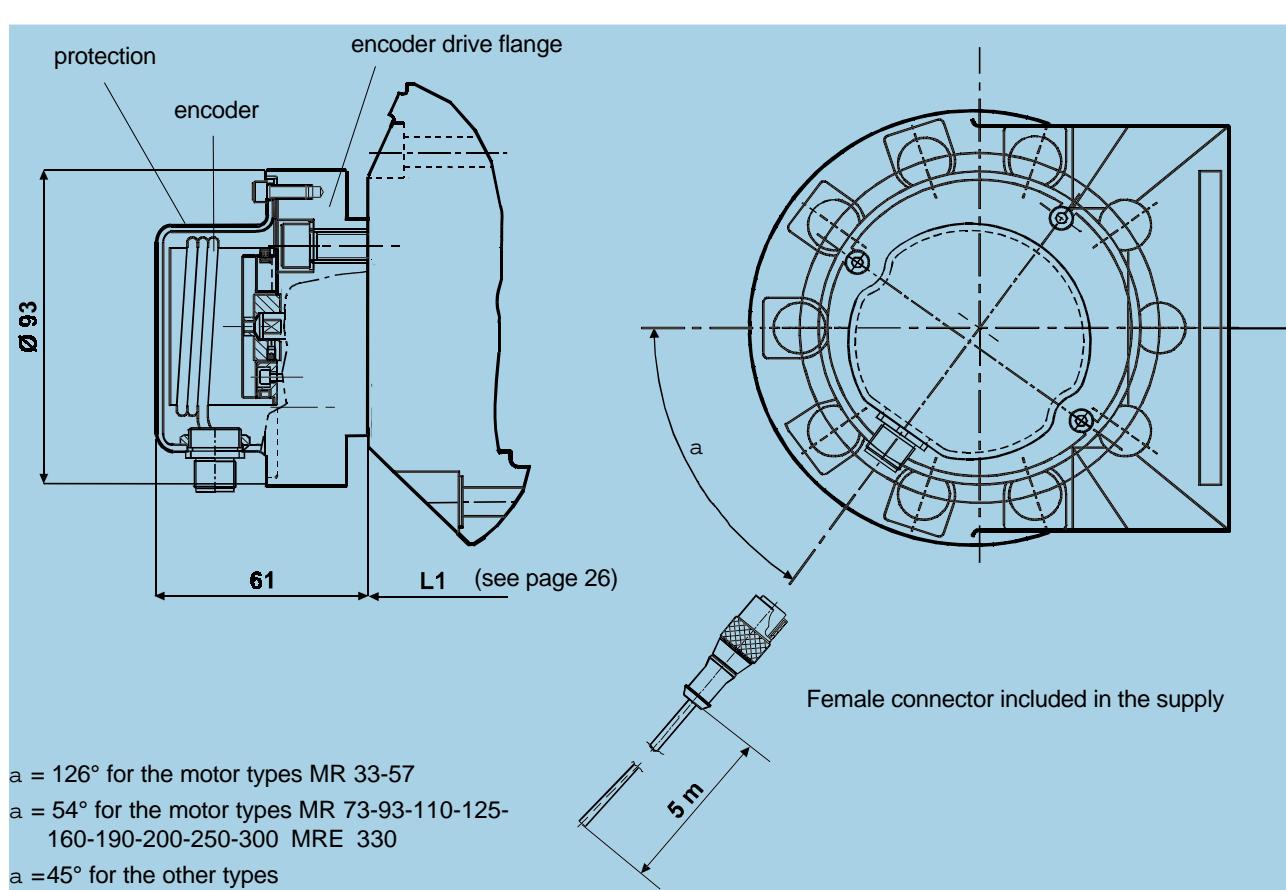
**MECHANICAL  
TACHOMETER DRIVE**

**TACHOGENERATOR  
DRIVE**

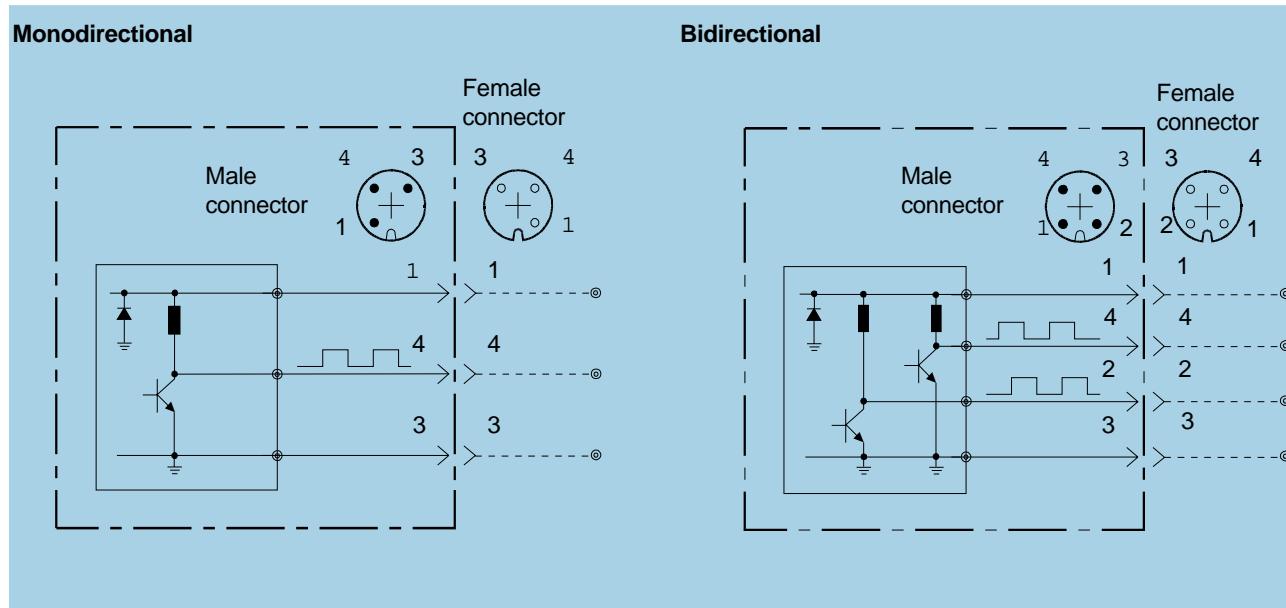
**ENCODER  
DRIVE**



**INCREMENTAL ENCODER  
DIMENSIONS**



## INCREMENTAL ENCODER CONNECTION DIAGRAMS



Color wires and function		
<b>1</b>	<b>Brown</b>	Power Supply (8 to 24 Vdc)
<b>2</b>	<b>White</b>	Output B phase (MAX 10 mA - 24 Vcc)
<b>3</b>	<b>Blue</b>	Power Supply (0 Vdc)
<b>4</b>	<b>Black</b>	Output A phase (MAX 10 mA - 24 Vcc)

## INCREMENTAL ENCODER TECHNICAL DATA

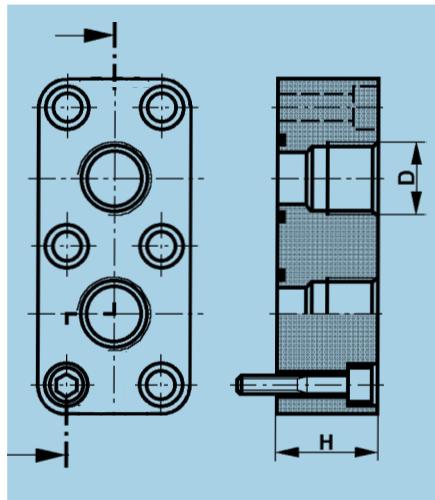
Encoder type:	ELCIS mod. 478
Supply voltage:	8 to 24 Vcc
Current consumption:	120 mA max
Current output:	10 mA max
Output signal:	A phase- MONODIRECTIONAL A and B phase BIDIRECTIONAL
Response frequency:	100 KHz max
Number of pulses:	500 (others on request - max 2540)
Slew speed:	Always compatible with maximum motor speed
Operating temperature range:	from 0 to 70 °C
Storage temperature range:	from -30 to +85 °C
Ball bearing life:	1.5x10 <sup>9</sup> rpm
Weigth:	100 gr
Protection degree:	IP 67 (with protection and connector assembled)
Connectors:	
MONODIRECTIONAL	RSF3/0.5 M (Lumberg) RKT3-06/5m (Lumberg)
BIDIRECTIONAL	RSF4/0.5 M (Lumberg) RKT4-07/5m (Lumberg)
	male female
	male female

Note: Female connectors cable length equal to 5 m.

## STANDARD CONNECTION FLANGE

Code "C1"

Flange is supplied complete with screws and seals.



MR MRE	D (BSP)	H	CODE NBR	CODE FPM
<b>125 - 160</b> 190 200 - 250 300 - 330	3/4"	36	262 098	229 394
<b>350 - 450</b> 500 600 - 700 800	1 1/4"	40	262 089	229 395
<b>1100 - 1400</b> 1600 - 1800 2100	1 1/2"	45	262 093	229 396
<b>2400 - 2800</b> 3100	1 1/2"	60	264 572	229 397
<b>3600 - 4500</b> 5400 6500 - 7000 8200	2"	60	272 724	229 398

BSP threads to ISO 228/1

Permitted up to 6000 PSI

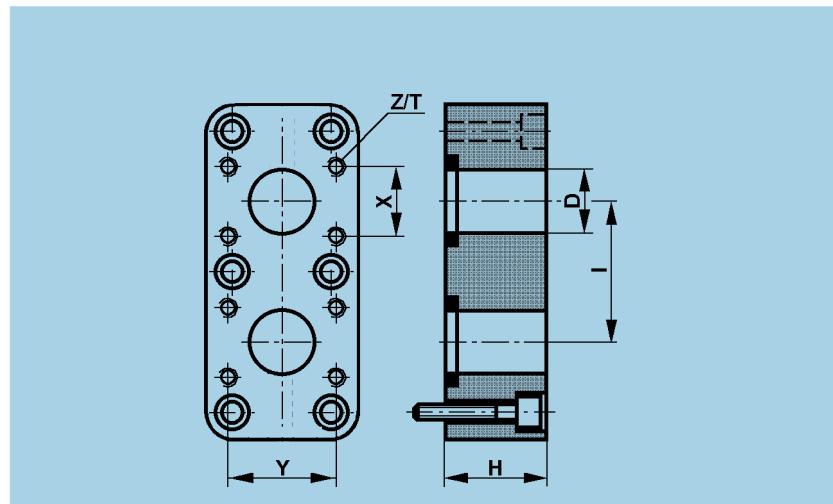
## SAE CONNECTION FLANGE

Codice "S1"

Codice "T1"

Codice "G1"

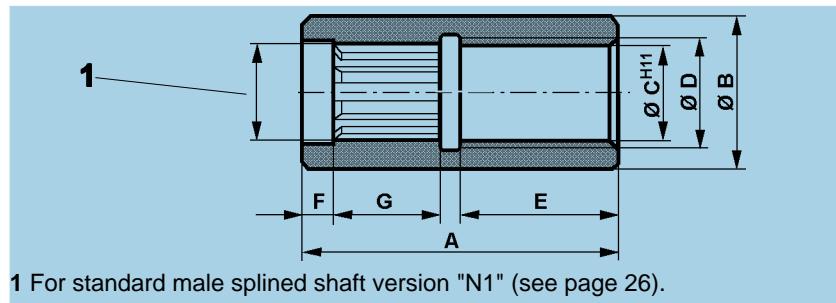
Codice "L1"



Flange is supplied complete with screws and seals. FPM seals enquiry.

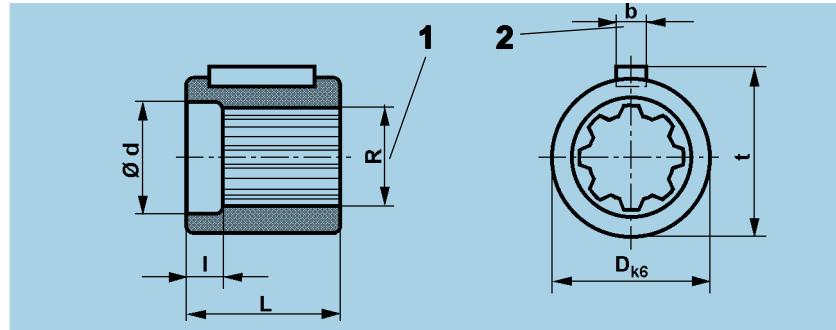
MR MRE	SAE PSI	D		H	I	X	Y	METRIC		UNC		
		"	mm					Z / T	Denison Calzoni part N° NBR	Z ("")	T	Denison Calzoni part N° NBR
<b>125 - 160</b> 190 200 - 250 300 - 330	5000	3/4"	19	36	55	22,2	47,6	M10/25	277 295	3/8"- 16	25	223 335
<b>350 - 450</b> 500 600 - 700 800	5000	1"	25	40	60	26,2	52,4	M10/25	277 297	3/8"- 16	25	223 336
<b>1100 - 1400</b> 1800 - 1600 2100	4000	1 1/4"	31	45	75	30,2	58,7	M10/25	277 299	7/16"- 14	30	223 337
	6000	1"	25	45	71	27,8	57,15	M12/22	230 166	7/16"- 14	30	342 092
<b>2400 - 2800</b> 3100	3000	1 1/2"	37	60	86	35,7	69,8	M12/30	277 301	1/2"- 13	30	223 338
	6000	1 1/2"	37	60	97,5	36,5	79,4	M16/30	230 168	5/8"- 11	35	349068
<b>3600 - 4500</b> 5400 6500 - 7000 8200	3000	2"	50	60	112	42,9	77,8	M12/30	277 303	1/2"- 13	30	223 339
	6000	2"	50	60	116	44,45	96,82	M20/35	230 170	3/4"- 10	38	342 547

## COUPLINGS



MR MRE	ORDERING CODE	A	B	C <sup>H11</sup>	D	E	F	G
<b>125 - 160</b> 190	465 203	114	56	39	47	54	15,5	34,5
<b>250 - 300</b> 330	465 202	135	71	49	60	64	15	45
<b>350 - 450</b> 500	465 201	155	80	55	68	68	18,5	55,5
<b>600 - 700</b> 800	465 200	171	90	61	75	80	19	59
<b>1100</b> 1400	464 785	186	106	73	88,5	85,5	20	65,5
<b>1600 - 1800</b> 2100	465 199	224	118	83	98	107	22	78
<b>2400 - 2800</b> 3100	465 198	265	132	93	112	127	23	97
<b>3600 - 4500</b> 5400	474 692	355	150	113	126	165	30	140
<b>6500 - 7000</b> 8200	422 544	390	195	126	140	185	38	147

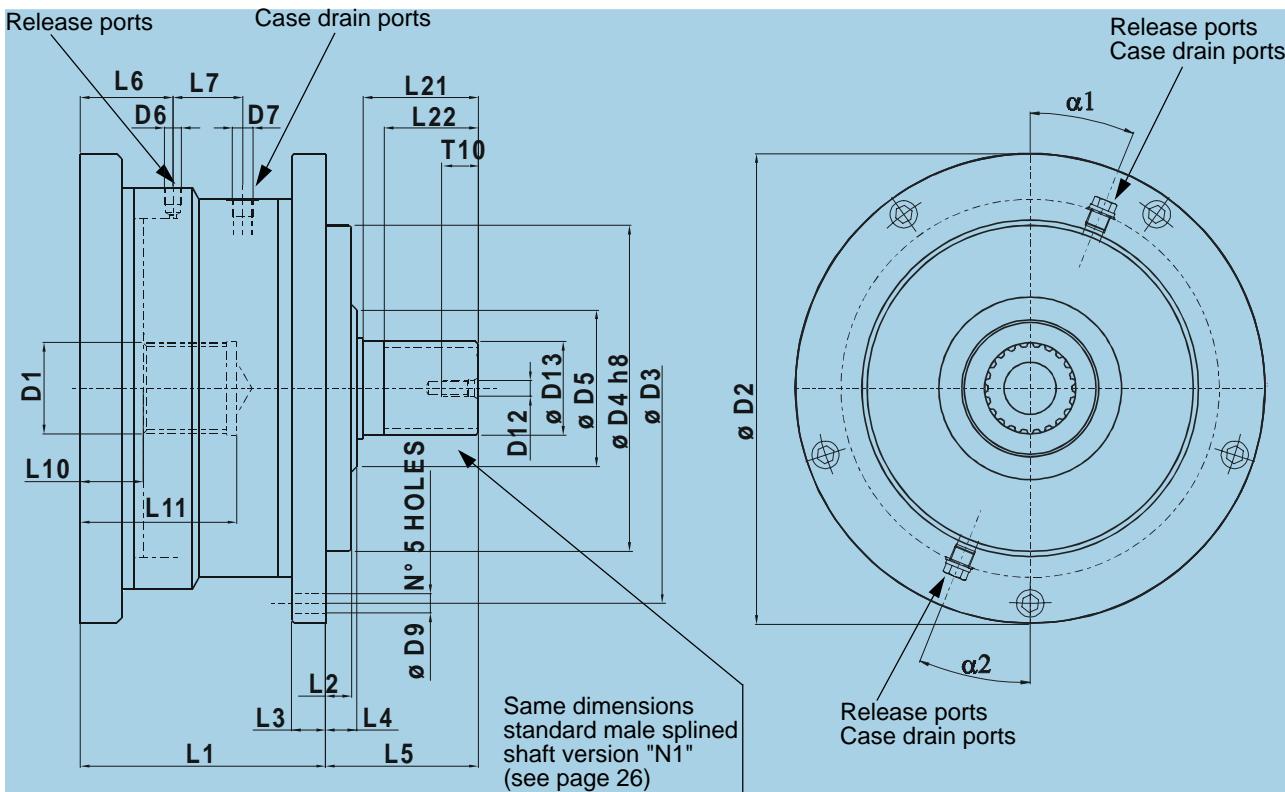
## ADAPTERS WITH KEY



MR MRE	ORDERING CODE	R EX DIN 5463 (mm)	d	I	D <sub>IS</sub>	L	b	t	Key (mm) DIN 6885
<b>125 - 160</b> 190	271 117	A8x32x38	38,3	15,5	58	50	10	61	10x8x45
<b>250 - 300</b> 330	271 118	A8x42x48	48,3	15	70	60	14	73,5	14x9x56
<b>350 - 450</b> 500	271 119	A8x46x54	54,3	18,5	80	75	16	84	16x10x70
<b>600 - 700</b> 800	271 120	A8x52x60	60,3	19	90	80	18	94	18x11x70
<b>1100 - 1400</b>	271 121	A8x62x72	72,3	20	105	98	20	109,5	20x12x90
<b>1600 - 1800</b> 2100	271 122	A10x72x82	82,3	22	118	118	22	123	22x14x110
<b>2400 - 2800</b> 3100	271 123	A10x82x92	92,3	23	130	148	25	135	25x14x140
<b>3600 - 4500</b> 5400	272 719	A10x102x112	112,3	30	160	188	28	166	28x16x180
<b>6500 - 7000</b> 8200	223 476	A10x112x125	126,6	38	185	188	45	195	45x25x180

# HOLDING BRAKE UNIT DIMENSIONS - MOTOR TYPE MR - MRE

BRAKE TYPE	B 190	B 300	B 450	B 700	B 1100	B 1800	B 2800
MOTOR TYPE MR - MRE	125 - 160 190	250 - 300 330	350 - 450 500	600 - 700 800	1100 - 1400	1600 - 1800 2100	2400 - 2800 3100



$\alpha_1, \alpha_2$  Corresponding angles to the release ports 1 and 2, to case the drain ports 1 and 2

BRAKE TYPE	L1	L2	L3	L4	L5	L6	L7	L10	L11	L12	L22	D1	D2	D3	D4 <sub>h8</sub>	D5	D6	D7	D9	D12	D13	T10	$\alpha_1$	$\alpha_2$
B 190	121	-	22	14	67	41	29,3	20	72	50	35,5	N 38x2x18-9H DIN 5480	250	225	160	-	G1/4"	G3/8"	10,5	M12	B 8x32x38 ex DIN 5463	28	22°30'	22°30'
B 300	136	-	25	15	81	42	39,5	21	86	60	46	N 48x2x22-9H DIN 5480	256	232	175	-	G1/4"	G3/8"	10,5	M12	B 8x42x48 ex DIN 5463	28	22°30'	22°30'
B 450	147	-	27	15	97	49,5	36	24	100	74	56,5	N 55x3x17-9H DIN 5480	296	266	190	-	G1/4"	G3/8"	13,5	M12	B 8x46x54 ex DIN 5463	28	22°30'	22°30'
B 700	172	-	28	15	101	55	46	25	105	78	62	N 60x3x18-9H DIN 5480	320	290	220	-	G1/4"	G3/8"	13,5	M12	B 8x52x60 ex DIN 5463	28	22°30'	22°30'
B 1100	188	20	26	24	117	71	53,5	48	120	88	72	N 70x3x22-9H DIN 5480	360	330	250	120	G1/4"	M16-x1,5	15	M12	B 8x62x72 ex DIN 5463	28	0°	0°
B 1800	216	-	28	21	132	63,5	58,5	34	135	100	79	N 80x3x25-9H DIN 5480	423	380	290	-	G1/4"	G1/2'	17,5	M12	B 10x72x82 ex DIN 5463	28	22°30'	22°30'
B 2800	263	-	30	24	153	87	67	42,5	165	120	99	N 90x4x21-9H DIN 5480	494	440	335	-	G1/4"	G1/2'	19	M12	B 10x82x92 ex DIN 5463	28	22°30'	22°30'

## TECHNICAL DATA

(For operation outside these parameters, please consult **DENISON Calzoni**)

CHARACTERISTICS		BRAKE TYPE						
		B 190	B 300	B 450	B 700	B 1100	B 1800	B 2800
<b>STATIC BRAKING TORQUE</b>	<b>Nm</b>	1250	1800	2650	4000	6200	11400	17100
<b>DYNAMIC BRAKING TORQUE</b>	<b>Nm</b>	870	1200	1450	2200	4200	6250	12000
<b>RELEASE PRESSURE</b>	<b>bar</b>	28	28	27	27	27	30	30
<b>MAX. OPERATING PRESSURE</b>	<b>bar</b>	420	420	420	420	420	420	420
<b>MOMENT OF INERTIA OF ROTATING PARTS</b>	<b>Kgm<sup>2</sup></b>	0,0047	0,0062	0,029	0,043	0,061	0,20	0,27
<b>WEIGHT</b>	<b>Kg</b>	32	39	54	74	100	158	262
<b>MOTOR TYPE MR MRE</b>		125 160 190	250 300 330	350 450 500	600 700 800	1100 1400	1600 1800 2100	2400 2800 3100

## CODE

Example: BRAKE - B 450 - N1 V1 \*\*

1. BRAKE - **B 450 NI V1 \*\***

## BRAKE TYPE

<b>B 190</b>	Brake for motor size "C"
<b>B 300</b>	Brake for motor size "D"
<b>B 450</b>	Brake for motor size "E"
<b>B 700</b>	Brake for motor size "F"
<b>B 1100</b>	Brake for motor size "G"
<b>B 1800</b>	Brake for motor size "H"
<b>B 2800</b>	Brake for motor size "I"

2. BRAKE - B 450 - **N1 V1 \*\***

## SHAFT

<b>N1</b>	Spline ex DIN 5463 (see page 26)
<b>D1 *</b>	Spline DIN 5480 (see page 26)
<b>F1 *</b>	Female spline DIN 5480 (see page 27)
<b>* please contact DENISON Calzoni</b>	

3. BRAKE - B 450 - **N1 V1 \*\***

## SEALS

<b>N1</b>	NBR: mineral oil
<b>V1 *</b>	FPM seals
<b>U1</b>	No shaft seal (for brake)
<b>* please contact DENISON Calzoni</b>	

4. BRAKE - B 450 - **N1 V1 \*\***

## SPECIAL

<b>**</b>	Space reserved to Denison Calzoni
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## Mounting

Any mounting position

- Note the position of the case drain port (see below)

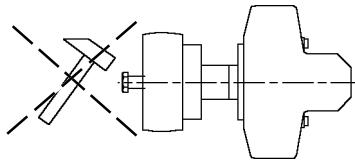
Install the motor properly

- Mounting surface must be flat and resistant to bending

Min. tensile strength of mounting screws to DIN 267 Part 3 class 10.9

- Note the prescribed fastening torque

## Coupling



- Mounting with screws
- Use threaded bore in the drive shaft
- Take apart with extractor

## Pipes, pipe connections

Use suitable screws!

- Depending on type of motor use either threaded or flange connection

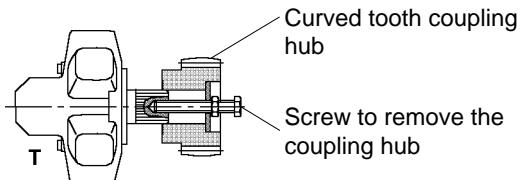
Choose pipes and hoses suitable for the installation

- Please note manufacturing data!

Before operation fill with hydraulic fluid

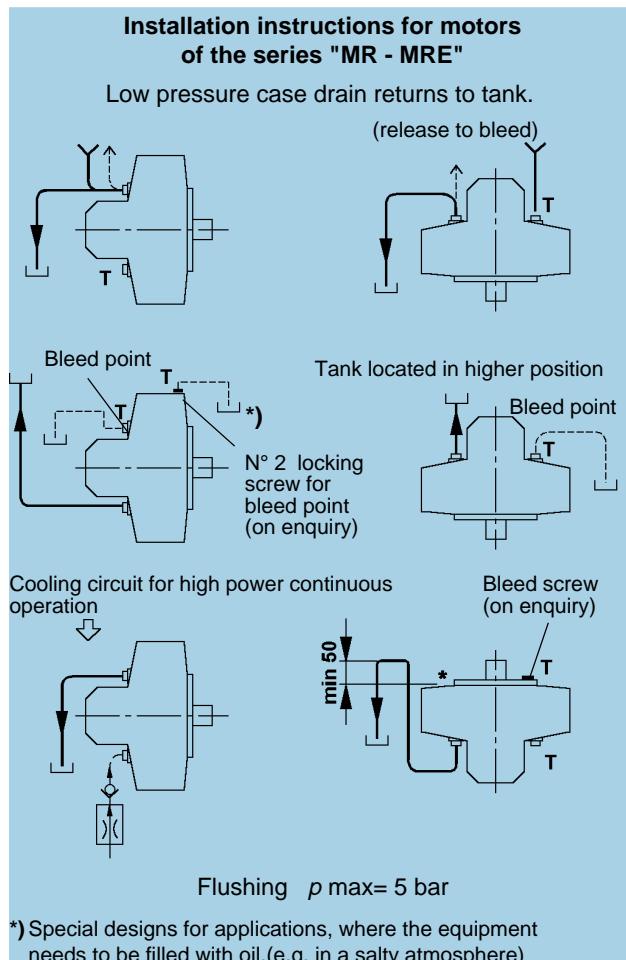
- Use the prescribed filter!

**NOTE:** Two of the mounting screws must be precisely located/fitted if operation is started and stopped frequently or if high reversible frequencies exist.



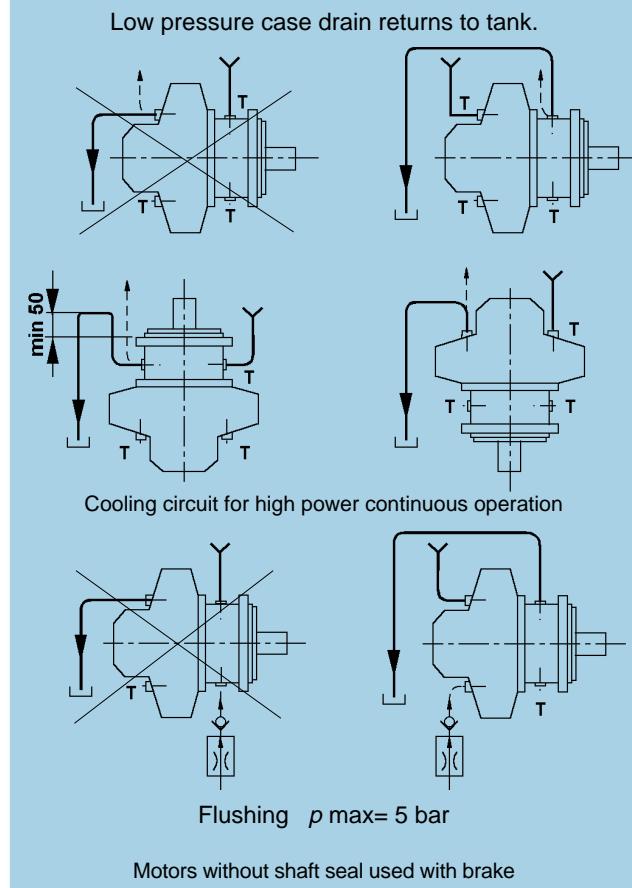
## DRAIN AND FLUSHING LINK INSTALLATION EXAMPLES

**Note:** Position the case drain pipe, so that the motor **cannot run** empty.



T = Seal  
Y = Motor housing feeding line  
← = Bleed

### Installation instructions for motors of the series "MR - MRE with brakes"



**CODE**

**1. MR 160C - N1 M1 F1 N1 N \*\*  
SERIES**

**2. MR 160C - N1 M1 F1 N1 N \*\***

**SIZE & DISPLACEMENT**

**3. MR 160C - N1 M1 F1 N1 N \*\***

**SHAFT**

**4. MR 160C - N1 M1 F1 N1 N \*\***

**SPEED SENSOR OPTION**

**5. MR 160C - N1 M1 F1 N1 N \*\***

**SEALS**

**6. MR 160C - N1 M1 F1 N1 N \*\***

**CONNECTION FLANGE**

**7. MR 160C - N1 M1 F1 N1 N \*\***

**ROTATION**

**8. MR 160C - N1 M1 F1 N1 N \*\*  
SPECIAL**

**Example: MR 160C - N1 M1 F1 N1 N \*\***

<b>MR</b>	standard 250 bar max. continuous
<b>MRE</b>	expanded 210 bar max. continuous

<b>A</b>	code	<b>MR 33 A</b>	<b>MR 57 A</b>		
	Cm <sup>3</sup>	32,1	56,4		
<b>B</b>	code	<b>MR 73 B</b>	<b>MR 93 B</b>	<b>MR110 B</b>	
	Cm <sup>3</sup>	72,6	92,6	109,0	
<b>C</b>	code	<b>MR 125 C</b>	<b>MR 160 C</b>	<b>MR 190 C</b>	
	Cm <sup>3</sup>	124,7	159,7	191,6	
<b>D</b>	code	<b>MR 200 D</b>	<b>MR 250 D</b>	<b>MR 300 D</b>	<b>MRE 330 D</b>
	Cm <sup>3</sup>	199,2	250,9	304,1	332,4
<b>E</b>	code	<b>MR 350 E</b>	<b>MR 450 E</b>	<b>MRE 500 E</b>	
	Cm <sup>3</sup>	349,5	451,6	497,9	
<b>F</b>	code	<b>MR 600 F</b>	<b>MR 700 F</b>	<b>MRE 800 F</b>	
	Cm <sup>3</sup>	607,9	706,9	804,2	
<b>G</b>	code	<b>MR 1100 G</b>	<b>MRE 1400 G</b>		
	Cm <sup>3</sup>	1125,8	1369,5		
<b>H</b>	code	<b>MR 1600 H</b>	<b>MR 1800 H</b>	<b>MRE 2100 H</b>	
	Cm <sup>3</sup>	1598,4	1809,6	2091,2	
<b>I</b>	code	<b>MR 2400 I</b>	<b>MR 2800 I</b>	<b>MRE 3100 I</b>	
	Cm <sup>3</sup>	2393,0	2792,0	3103,7	
<b>L</b>	code	<b>MR 3600 L</b>	<b>MR 4500 L</b>	<b>MRE 5400 L</b>	
	Cm <sup>3</sup>	3636,8	4502,7	5401,2	
<b>M</b>	code	<b>MR 6500 M</b>	<b>MR 7000 M</b>	<b>MRE 8200 M</b>	
	Cm <sup>3</sup>	6460,5	6967,2	8226,4	

<b>N1</b>	spline ex DIN 5463 (see page 26)
<b>D1</b>	spline DIN 5480 ((see page 26)
<b>F1</b>	female spline DIN 5480 (see page 27)
<b>P1</b>	shaft with key (see page 27)
<b>B1</b>	spline B.S. 3550 (see page 26)

<b>N1</b>	none	
<b>Q1</b>	encoder drive (see page 28)	
<b>C1</b>	mechanical tachometer drive (see page 28)	
<b>T1</b>	tachogenerator drive (see page 28)	
<b>M1</b>	incremental Elcis encoder ( 500 pulse/rev) (see page 28)	Uni-directional
<b>B1</b>		Bi-directional

<b>N1</b>	NBR mineral oil
<b>F1</b>	NBR, 15 bar shaft seal
<b>V1</b>	FPM seals
<b>U1</b>	no shaft seal (for brake)

<b>N1</b>	none
<b>C1</b>	standard DENISON Calzoni (see page 30)
<b>S1</b>	standard SAE metric (see page 30)
<b>T1</b>	standard SAE UNC (see page 30)
<b>G1</b>	SAE 6000 psi metric (see page 30)
<b>L1</b>	SAE 6000 psi UNC (see page 30)

<b>N</b>	standard rotation (CW: inlet in A, CCW: inlet in B)
<b>S</b>	reversed rotation (CW: inlet in B, CCW: inlet in A)

<b>**</b>	space reserved to Denison Calzoni
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**DENISON CALZONI**